The OpenACC®
Application Programming Interface

Version 2.6 Public Review Document
Please send corrections or suggestions to feedback@openacc.org

OpenACC-Standard.org

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1. Introduction

This document describes the compiler directives, library routines, and environment variables that collectively define the OpenACC™ Application Programming Interface (OpenACC API) for offloading programs written in C, C++, and Fortran programs from a host CPU to an attached accelerator device. The method described provides a model for accelerator programming that is portable across operating systems and various types of host CPUs and accelerators. The directives extend the ISO/ANSI standard C, C++, and Fortran base languages in a way that allows a programmer to migrate applications incrementally to accelerator targets using standards-based C, C++, or Fortran. The directives and programming model defined in this document allow programmers to create applications capable of using accelerators without the need to explicitly manage data or program transfers between the host and accelerator or to initiate accelerator startup and shutdown. Rather, these details are implicit in the programming model and are managed by the OpenACC API-enabled compilers and runtime environments. The programming model allows the programmer to augment information available to the compilers, including specification of data local to an accelerator, guidance on mapping of loops onto an accelerator, and similar performance-related details.

1.1. Scope

This OpenACC API document covers only user-directed accelerator programming, where the user specifies the regions of a host program to be targeted for offloading to an accelerator device. The remainder of the program will be executed on the host. This document does not describe features or limitations of the host programming environment as a whole; it is limited to specification of loops and regions of code to be offloaded to an accelerator.

This document does not describe automatic detection and offloading of regions of code to an accelerator by a compiler or other tool. This document does not describe splitting loops or code regions to multiple accelerators attached to a single host. While future compilers may allow for automatic offloading, or offloading to multiple accelerators of the same type, or to multiple accelerators of different types, these possibilities are not addressed in this document.

1.2. Execution Model

The execution model targeted by OpenACC API-enabled implementations is host-directed execution with an attached accelerator device, such as a GPU. Much of a user application executes on the host. Compute intensive regions are offloaded to the accelerator device under control of the host. The device executes parallel regions, which typically contain work-sharing loops, kernels regions, which typically contain one or more loops which are executed as kernels on the accelerator, or serial regions, which are blocks of sequential code that execute on the accelerator. Even in accelerator-targeted regions, the host may orchestrate the execution by allocating memory on the accelerator
device, initiating data transfer, sending the code to the accelerator, passing arguments to the compute region, queuing the device code, waiting for completion, transferring results back to the host, and deallocating memory. In most cases, the host can queue a sequence of operations to be executed on the device, one after the other.

Most current accelerators support two or three levels of parallelism. Most accelerators support coarse-grain parallelism, which is fully parallel execution across execution units. There may be limited support for synchronization across coarse-grain parallel operations. Many accelerators also support fine-grain parallelism, often implemented as multiple threads of execution within a single execution unit, which are typically rapidly switched on the execution unit to tolerate long latency memory operations. Finally, most accelerators also support SIMD or vector operations within each execution unit. The execution model exposes these multiple levels of parallelism on the device and the programmer is required to understand the difference between, for example, a fully parallel loop and a loop that is vectorizable but requires synchronization between statements. A fully parallel loop can be programmed for coarse-grain parallel execution. Loops with dependences must either be split to allow coarse-grain parallel execution, or be programmed to execute on a single execution unit using fine-grain parallelism, vector parallelism, or sequentially.

OpenACC exposes these three levels of parallelism via gang, worker, and vector parallelism. Gang parallelism is coarse-grain. A number of gangs will be launched on the accelerator. Worker parallelism is fine-grain. Each gang will have one or more workers. Vector parallelism is for SIMD or vector operations within a worker.

When executing a compute region on the device, one or more gangs are launched, each with one or more workers, where each worker may have vector execution capability with one or more vector lanes. The gangs start executing in gang-redundant mode (GR mode), meaning one vector lane of one worker in each gang executes the same code, redundantly. When the program reaches a loop or loop nest marked for gang-level work-sharing, the program starts to execute in gang-partitioned mode (GP mode), where the iterations of the loop or loops are partitioned across gangs for truly parallel execution, but still with only one worker per gang and one vector lane per worker active.

When only one worker is active, in either GR or GP mode, the program is in worker-single mode (WS mode). When only one vector lane is active, the program is in vector-single mode (VS mode). If a gang reaches a loop or loop nest marked for worker-level work-sharing, the gang transitions to worker-partitioned mode (WP mode), which activates all the workers of the gang. The iterations of the loop or loops are partitioned across the workers of this gang. If the same loop is marked for both gang-partitioning and worker-partitioning, then the iterations of the loop are spread across all the workers of all the gangs. If a worker reaches a loop or loop nest marked for vector-level work-sharing, the worker will transition to vector-partitioned mode (VP mode). Similar to WP mode, the transition to VP mode activates all the vector lanes of the worker. The iterations of the loop or loops will be partitioned across the vector lanes using vector or SIMD operations. Again, a single loop may be marked for one, two, or all three of gang, worker, and vector parallelism, and the iterations of that loop will be spread across the gangs, workers, and vector lanes as appropriate.

The program starts executing with a single host thread, identified by a program counter and its stack. The thread may spawn additional host threads, for instance using the OpenMP API. On the accelerator device, a single vector lane of a single worker of a single gang is called a thread. When executing on the device, a parallel execution context is created on the accelerator and may contain many such threads.

The user should not attempt to implement barrier synchronization, critical sections or locks across...
any of gang, worker, or vector parallelism. The execution model allows for an implementation that executes some gangs to completion before starting to execute other gangs. This means that trying to implement synchronization between gangs is likely to fail. In particular, a barrier across gangs cannot be implemented in a portable fashion, since all gangs may not ever be active at the same time. Similarly, the execution model allows for an implementation that executes some workers within a gang or vector lanes within a worker to completion before starting other workers or vector lanes, or for some workers or vector lanes to be suspended until other workers or vector lanes complete. This means that trying to implement synchronization across workers or vector lanes is likely to fail. In particular, implementing a barrier or critical section across workers or vector lanes using atomic operations and a busy-wait loop may never succeed, since the scheduler may suspend the worker or vector lane that owns the lock, and the worker or vector lane waiting on the lock can never complete.

On some devices, the accelerator may also create and launch compute regions, allowing for nested parallelism. In that case, the OpenACC directives may be executed by a host thread or an accelerator thread. This specification uses the term local thread or local memory to mean the thread that executes the directive, or the memory associated with that thread, whether that thread executes on the host or on the accelerator.

Most accelerators can operate asynchronously with respect to the host thread. With such devices, the accelerator has one or more activity queues. The host thread will enqueue operations onto the device activity queues, such as data transfers and procedure execution. After enqueuing the operation, the host thread can continue execution while the device operates independently and asynchronously. The host thread may query the device activity queue(s) and wait for all the operations in a queue to complete. Operations on a single device activity queue will complete before starting the next operation on the same queue; operations on different activity queues may be active simultaneously and may complete in any order.

1.3. Memory Model

The most significant difference between a host-only program and a host+accelerator program is that the memory on the accelerator may be physically and/or virtually separate from host memory. This is the case with most current GPUs, for example. In this case, the host thread may not be able to read or write device memory directly because it is not mapped into the host thread’s virtual memory space. All data movement between host memory and device memory must be performed by the host thread through system calls that explicitly move data between the separate memories, typically using direct memory access (DMA) transfers. Similarly, it is not valid to assume the accelerator can read or write host memory, though this is supported by some accelerator devices, often with significant performance penalty.

The concept of separate host and accelerator memories is very apparent in low-level accelerator programming languages such as CUDA or OpenCL, in which data movement between the memories can dominate user code. In the OpenACC model, data movement between the memories can be implicit and managed by the compiler, based on directives from the programmer. However, the programmer must be aware of the potentially separate memories for many reasons, including but not limited to:

- Memory bandwidth between host memory and device memory determines the level of compute intensity required to effectively accelerate a given region of code.
• The user should be aware that a separate device memory is usually significantly smaller than
the host memory, prohibiting offloading regions of code that operate on very large amounts
of data.

• Host addresses stored to pointers on the host may only be valid on the host; addresses stored
to pointers on the device may only be valid on the device. Explicitly transferring pointer
values between host and device memory is not advised. Dereferencing host pointers on the
device or dereferencing device pointers on the host is likely to be invalid on such targets.

OpenACC exposes the separate memories through the use of a device data environment. Device
data has an explicit lifetime, from when it is allocated or created until it is deleted. If the device
shares physical and virtual memory with the local thread, the device data environment will be shared
with the local thread. In that case, the implementation need not create new copies of the data for
the device and no data movement need be done. If the device has a physically or virtually separate
memory from the local thread, the implementation will allocate new data in the device memory and
copy data from the local memory to the device environment.

Some accelerators (such as current GPUs) implement a weak memory model. In particular, they do
not support memory coherence between operations executed by different threads; even on the same
execution unit, memory coherence is only guaranteed when the memory operations are separated
by an explicit memory fence. Otherwise, if one thread updates a memory location and another reads
the same location, or two threads store a value to the same location, the hardware may not guarantee
the same result for each execution. While a compiler can detect some potential errors of this nature,
it is nonetheless possible to write a compute region that produces inconsistent numerical results.

Similarly, some accelerators implement a weak memory model for memory shared between the
host and the accelerator, or memory shared between multiple accelerators. Programmers need to
be very careful that the program uses appropriate synchronization to ensure that an assignment or
modification to shared data by a host thread is complete and available before that data is used by
an accelerator thread. Similarly, synchronization must be used to ensure that an assignment or
modification to shared data by an accelerator thread is complete and available before that data is
used by a host thread or by a thread on a different accelerator.

Some current accelerators have a software-managed cache, some have hardware managed caches,
and most have hardware caches that can be used only in certain situations and are limited to read-
only data. In low-level programming models such as CUDA or OpenCL languages, it is up to the
programmer to manage these caches. In the OpenACC model, these caches are managed by the
compiler with hints from the programmer in the form of directives.

1.4. Conventions used in this document

Keywords and punctuation that are part of the actual specification will appear in typewriter font:

`#pragma acc`

Italic font is used where a keyword or other name must be used:

`#pragma acc directive-name`

For C and C++, `new-line` means the newline character at the end of a line:
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1.5. Organization of this document

The rest of this document is organized as follows:

Chapter 2 Directives describes the C, C++, and Fortran directives used to delineate accelerator regions and augment information available to the compiler for scheduling of loops and classification of data.

Chapter 3 Runtime Library defines user-callable functions and library routines to query the accelerator device features and control behavior of accelerator-enabled programs at runtime.

Chapter 4 Environment Variables defines user-settable environment variables used to control behavior of accelerator-enabled programs at execution.

Chapter 5 Profiling Interface describes the OpenACC interface for tools that can be used for profile and trace data collection.

Chapter 6 Glossary defines common terms used in this document.

Appendix A Recommendations for Implementors gives advice to implementers to support more portability across implementations and interoperability with other accelerator APIs.

1.6. References

- OpenMP Application Program Interface, version 4.0, July 2013.
1.7. Changes from Version 1.0 to 2.0

- _OPENACC value updated to 201306
- default (none) clause on parallel and kernels directives
- the implicit data attribute for scalars in parallel constructs has changed
- the implicit data attribute for scalars in loops with loop directives with the independent attribute has been clarified
- acc_async_sync and acc_async_noval values for the async clause
- Clarified the behavior of the reduction clause on a gang loop
- Clarified allowable loop nesting (gang may not appear inside worker, which may not appear within vector)
- wait clause on parallel, kernels and update directives
- async clause on the wait directive
- enter data and exit data directives
- Fortran common block names may now be specified in many data clauses
- link clause for the declare directive
- the behavior of the declare directive for global data
- the behavior of a data clause with a C or C++ pointer variable has been clarified
- predefined data attributes
- support for multidimensional dynamic C/C++ arrays
- tile and auto loop clauses
- update self introduced as a preferred synonym for update host
- routine directive and support for separate compilation
- device_type clause and support for multiple device types
- nested parallelism using parallel or kernels region containing another parallel or kernels region
- atomic constructs
- new concepts: gang-redundant, gang-partitioned; worker-single, worker-partitioned; vector-single, vector-partitioned; thread
- new API routines:
  - acc_wait, acc_wait_all instead of acc_async_wait and acc_async_wait_all
  - acc_wait_async
1.8. Corrections in the August 2013 document

- corrected the atomic capture syntax for C/C++
- fixed the name of the acc_wait and acc_wait_all procedures
- fixed description of the acc_hostptr procedure

1.9. Changes from Version 2.0 to 2.5

- The _OPENACC value was updated to 201510; see Section 2.2 Conditional Compilation
- The num_gangs, num_workers, and vector_length clauses are now allowed on the kernels construct; see Section 2.5.2 Kernels Construct
- Reduction on C++ class members, array elements, and struct elements are explicitly disallowed; see Section 2.5.12 reduction clause
- Reference counting is now used to manage the correspondence and lifetime of device data; see Section 2.6.5 Reference Counting
- The behavior of the exit data directive has changed to decrement the dynamic reference count. A new optional finalize clause was added to set the dynamic reference count to zero. See Section 2.6.4 Enter Data and Exit Data Directives
- The copy, copyin, copyout, and create data clauses were changed to behave like present_or_copy, etc. The present_or_copy, pcopy, present_or_copyin, pcopyin, present_or_copyout, pcopyout, present_or_create, and pcreate data clauses are no longer needed, though will be accepted for compatibility; see Section 2.7 Data Clauses
- Reductions on orphaned gang loops are explicitly disallowed; see Section 2.9 Loop Construct
- The description of the loop auto clause has changed; see Section 2.9.6 auto clause
The OpenACC® API 1.10. Changes from Version 2.5 to 2.6

- Text was added to the `private` clause on a `loop` construct to clarify that a copy is made for each gang or worker or vector lane, not each thread; see Section 2.9.10 private clause.
- The description of the `reduction` clause on a `loop` construct was corrected; see Section 2.9.11 reduction clause.
- A restriction was added to the `cache` clause that all references to that variable must lie within the region being cached; see Section 2.10 Cache Directive.
- Text was added to the `private` and `reduction` clauses on a combined construct to clarify that they act like `private` and `reduction` on the `loop`, not `private` and `reduction` on the `parallel` or `reduction` on the `kernels`; see Section 2.11 Combined Constructs.
- The `declare create` directive with a Fortran `allocatable` has new behavior; see Section 2.13.2 create clause.
- A new `if_present` clause was added to the `update` directive, which changes the behavior when data is not present from a runtime error to a no-op; see Section 2.14.4 Update Directive.
- The `routine bind` clause definition changed; see Section 2.15.1 Routine Directive.
- An `acc routine` without `gang/worker/vector/seq` is now defined as an error; see Section 2.15.1 Routine Directive.
- A new `default(present)` clause was added for compute constructs; see Section 2.5.13 default clause.
- The Fortran header file `openacc_lib.h` is no longer supported; the Fortran module `openacc` should be used instead; see Section 3.1 Runtime Library Definitions.
- New API routines were added to get and set the default async queue value; see Section 3.2.15 `acc_get_default_async` and 3.2.16 `acc_set_default_async`.
- The `acc_copyin, acc_create, acc_copyout, and acc_delete` API routines were changed to behave like `acc_present_or_copyin` etc. The `acc_present_or_` names are no longer needed, though will be supported for compatibility. See Sections 3.2.20 and following.
- Asynchronous versions of the data API routines were added; see Sections 3.2.20 and following.
- A new API routine added, `acc_memcpy_device`, to copy from one device address to another device address; see Section 3.2.31 `acc_memcpy_to_device`.
- A new OpenACC interface for profile and trace tools was added; see Chapter 5 Profiling Interface.

1.10. Changes from Version 2.5 to 2.6

- The `_OPENACC` value was updated to 201711.
- A new `serial` compute construct was added. See Section 2.5.3 Serial Construct.
- A new runtime API query routine was added. `acc_get_property` may be called from
the host and returns properties about any device. See Section 3.2.6.

- The text has clarified that if a variable is in a reduction which spans two or more nested loops, each loop directive on any of those loops must have a reduction clause that contains the variable; see Section 2.9.11 reduction clause.
- An optional if or if_present clause is now allowed on the host_data construct. See Section 2.8 Host Data Construct.
- A new no_create data clause is now allowed on compute and data constructs. See Section 2.7.9 no_create clause.
- The behavior of Fortran optional arguments in data clauses and in routine calls has been specified; see Section 2.17 Fortran Optional Arguments.
- The descriptions of some of the Fortran versions of the runtime library routines were simplified; see Section 3.2 Runtime Library Routines.
- New attach and detach behavior was added to the data clauses, new attach and detach clauses were added, and matching acc_attach and acc_detach runtime API routines were added.
- The Intel Coprocessor Offload Interface target and API routine sections were removed from the Section A Recommendations for Implementors since Intel no longer produces this product.

1.11. Topics Deferred For a Future Revision

The following topics are under discussion for a future revision. Some of these are known to be important, while others will depend on feedback from users. Readers who have feedback or want to participate may post a message at the forum at www.openacc.org, or may send email to technical@openacc.org or feedback@openacc.org. No promises are made or implied that all these items will be available in the next revision.

- Full support for C and C++ structs and struct members, including pointer members.
- Full support for Fortran derived types and derived type members, including allocatable and pointer members.
- Fully defined interaction with multiple host threads.
- Optionally removing the synchronization or barrier at the end of vector and worker loops.
- Allowing an if clause after a device_type clause.
- A shared clause (or something similar) for the loop directive.
- Better support for multiple devices from a single thread, whether of the same type or of different types.
2. Directives

This chapter describes the syntax and behavior of the OpenACC directives. In C and C++, OpenACC directives are specified using the \#pragma mechanism provided by the language. In Fortran, OpenACC directives are specified using special comments that are identified by a unique sentinel. Compilers will typically ignore OpenACC directives if support is disabled or not provided.

2.1. Directive Format

In C and C++, OpenACC directives are specified with the \#pragma mechanism. The syntax of an OpenACC directive is:

\#pragma acc directive-name [clause-list] new-line

Each directive starts with \#pragma acc. The remainder of the directive follows the C and C++ conventions for pragmas. White space may be used before and after the \#; white space may be required to separate words in a directive. Preprocessing tokens following the \#pragma acc are subject to macro replacement. Directives are case-sensitive.

In Fortran, OpenACC directives are specified in free-form source files as

\$acc directive-name [clause-list]

The comment prefix (!) may appear in any column, but may only be preceded by white space (spaces and tabs). The sentinel (\$acc) must appear as a single word, with no intervening white space. Line length, white space, and continuation rules apply to the directive line. Initial directive lines must have white space after the sentinel. Continued directive lines must have an ampersand (&) as the last nonblank character on the line, prior to any comment placed in the directive. Continuation directive lines must begin with the sentinel (possibly preceded by white space) and may have an ampersand as the first non-white space character after the sentinel. Comments may appear on the same line as a directive, starting with an exclamation point and extending to the end of the line. If the first nonblank character after the sentinel is an exclamation point, the line is ignored.

In Fortran fixed-form source files, OpenACC directives are specified as one of

\$acc directive-name [clause-list]
\cacc directive-name [clause-list]
\$acc directive-name [clause-list]

The sentinel (\$acc, \cacc, or \$acc) must occupy columns 1-5. Fixed form line length, white space, continuation, and column rules apply to the directive line. Initial directive lines must have
a space or zero in column 6, and continuation directive lines must have a character other than a space or zero in column 6. Comments may appear on the same line as a directive, starting with an exclamation point on or after column 7 and continuing to the end of the line.

In Fortran, directives are case-insensitive. Directives cannot be embedded within continued statements, and statements must not be embedded within continued directives. In this document, free form is used for all Fortran OpenACC directive examples.

Only one directive-name can be specified per directive, except that a combined directive name is considered a single directive-name. The order in which clauses appear is not significant unless otherwise specified. Clauses may be repeated unless otherwise specified. Some clauses have an argument that can contain a list.

2.2. Conditional Compilation

The _OPENACC macro name is defined to have a value yyyyymm where yyyy is the year and mm is the month designation of the version of the OpenACC directives supported by the implementation. This macro must be defined by a compiler only when OpenACC directives are enabled. The version described here is 201711.

2.3. Internal Control Variables

An OpenACC implementation acts as if there are internal control variables (ICVs) that control the behavior of the program. These ICVs are initialized by the implementation, and may be given values through environment variables and through calls to OpenACC API routines. The program can retrieve values through calls to OpenACC API routines.

The ICVs are:

- acc-device-type-var - controls which type of accelerator device is used.
- acc-device-num-var - controls which accelerator device of the selected type is used.
- acc-default-async-var - controls which asynchronous queue is used when none is specified in an async clause.

2.3.1. Modifying and Retrieving ICV Values

The following table shows environment variables or procedures to modify the values of the internal control variables, and procedures to retrieve the values:
The initial values are implementation-defined. After initial values are assigned, but before any OpenACC construct or API routine is executed, the values of any environment variables that were set by the user are read and the associated ICVs are modified accordingly. Clauses on OpenACC constructs do not modify the ICV values. There is one copy of each ICV for each host thread. An ICV value for a device thread may not be modified.

2.4. Device-Specific Clauses

OpenACC directives can specify different clauses or clause arguments for different accelerators using the `device_type` clause. The argument to the `device_type` is a comma-separated list of one or more accelerator architecture name identifiers, or an asterisk. A single directive may have one or several `device_type` clauses. Clauses on a directive with no `device_type` apply to all accelerator device types. Clauses that follow a `device_type` up to the end of the directive or up to the next `device_type` are associated with this `device_type`. Clauses associated with a `device_type` apply only when compiling for the accelerator device type named. Clauses associated with a `device_type` that has an asterisk argument apply to any accelerator device type that was not named in any `device_type` on that directive. The `device_type` clauses may appear in any order. For each directive, only certain clauses may follow a `device_type`.

Clauses that precede any `device_type` are default clauses. Clauses that follow a `device_type` are device-specific clauses. A clause may appear both as a default clause and as a device-specific clause. In that case, the value in the device-specific clause is used when compiling for that device type.

The supported accelerator device types are implementation-defined. Depending on the implementation and the compiling environment, an implementation may support only a single accelerator device type, or may support multiple accelerator device types but only one at a time, or many support multiple accelerator device types in a single compilation.

An accelerator architecture name may be generic, such as a vendor, or more specific, such as a particular generation of device; see Appendix A[Recommendations for Implementors] for recommended names. When compiling for a particular device, the implementation will use the clauses associated with the `device_type` clause that specifies the most specific architecture name that applies for this device; clauses associated with any other `device_type` clause are ignored. In this context, the asterisk is the least specific architecture name.

**Syntax** The syntax of the `device_type` clause is
The device_type clause may be abbreviated to dtype.

2.5. Compute Constructs

2.5.1. Parallel Construct

Summary  This fundamental construct starts parallel execution on the current accelerator device.

Syntax  In C and C++, the syntax of the OpenACC parallel construct is

```
#pragma acc parallel [clause-list] new-line
structured block
```

and in Fortran, the syntax is

```
!$acc parallel [clause-list]
structured block
!$acc end parallel
```

where clause is one of the following:

- `async [( int-expr )]`
- `wait [( int-expr-list )]`
- `num_gangs( int-expr )`
- `num_workers( int-expr )`
- `vector_length( int-expr )`
- `device_type( device-type-list )`
- `if( condition )`
- `reduction( operator:var-list )`
- `copy( var-list )`
- `copyin( var-list )`
- `copyout( var-list )`
- `create( var-list )`
- `no_create( var-list )`
- `present( var-list )`
- `deviceptr( var-list )`
- `attach( var-list )`
- `private( var-list )`
- `firstprivate( var-list )`
- `default( none | present )`
Description  When the program encounters an accelerator `parallel` construct, one or more gangs of workers are created to execute the accelerator parallel region. The number of gangs, and the number of workers in each gang and the number of vector lanes per worker remain constant for the duration of that parallel region. Each gang begins executing the code in the structured block in gang-redundant mode. This means that code within the parallel region, but outside of a loop with a `loop` directive and gang-level worksharing, will be executed redundantly by all gangs.

One worker in each gang begins executing the code in the structured block of the construct. Note: Unless there is an explicit `loop` directive within the parallel region, all gangs will execute all the code within the region redundantly.

If the `async` clause is not present, there is an implicit barrier at the end of the accelerator parallel region, and the execution of the local thread will not proceed until all gangs have reached the end of the parallel region.

If there is no `default(none)` clause on the construct, the compiler will implicitly determine data attributes for variables that are referenced in the compute construct that do not have predetermined data attributes and do not appear in a data clause on the compute construct, a lexically containing `data` construct, or a visible `declare` directive. If there is no `default(present)` clause on the construct, an array or variable of aggregate data type referenced in the `parallel` construct that does not appear in a data clause for the construct or any enclosing `data` construct will be treated as if it appeared in a `copy` clause for the `parallel` construct. If there is a `default(present)` clause on the construct, the compiler will implicitly treat all arrays and variables of aggregate data type without predetermined data attributes as if they appeared in a `present` clause. A scalar variable referenced in the `parallel` construct that does not appear in a data clause for the construct or any enclosing `data` construct will be treated as if it appeared in a `firstprivate` clause.

Restrictions

- A program may not branch into or out of an OpenACC `parallel` construct.
- A program must not depend on the order of evaluation of the clauses, or on any side effects of the evaluations.
- Only the `async`, `wait`, `num_gangs`, `num_workers`, and `vector_length` clauses may follow a `device_type` clause.
- At most one `if` clause may appear. In Fortran, the condition must evaluate to a scalar logical value; in C or C++, the condition must evaluate to a scalar integer value.
- At most one `default` clause may appear, and it must have a value of either `none` or `present`.

The `copy`, `copyin`, `copyout`, `create`, `no_create`, `present`, `deviceptr`, and `attach` data clauses are described in Section 2.7 Data Clauses. The `private` and `firstprivate` clauses are described in Sections 2.5.10 and Sections 2.5.11. The `device_type` clause is described in Section 2.4 Device-Specific Clauses.

2.5.2. Kernels Construct

Summary  This construct defines a region of the program that is to be compiled into a sequence of kernels for execution on the current accelerator device.
In C and C++, the syntax of the OpenACC kernels construct is

```
#pragma acc kernels [clause-list] new-line
structured block
```

And in Fortran, the syntax is

```
!$acc kernels [clause-list]
structured block
!$acc end kernels
```

where clause is one of the following:

- async[(int-expr)]
- wait[(int-expr-list)]
- num_gangs(int-expr)
- num_workers(int-expr)
- vector_length(int-expr)
- device_type(device-type-list)
- if(condition)
- copy(var-list)
- copyin(var-list)
- copyout(var-list)
- create(var-list)
- no_create(var-list)
- present(var-list)
- deviceptr(var-list)
- attach(var-list)
- default(none | present)

The compiler will split the code in the kernels region into a sequence of accelerator kernels. Typically, each loop nest will be a distinct kernel. When the program encounters a kernels construct, it will launch the sequence of kernels in order on the device. The number and configuration of gangs of workers and vector length may be different for each kernel.

If the async clause is not present, there is an implicit barrier at the end of the kernels region, and the local thread execution will not proceed until all kernels have completed execution.

If there is no default(none) clause on the construct, the compiler will implicitly determine data attributes for variables that are referenced in the compute construct that do not have predetermined data attributes and do not appear in a data clause on the compute construct, a lexically containing data construct, or a visible declare directive. If there is no default(present) clause on the construct, an array or variable of aggregate data type referenced in the kernels construct that does not appear in a data clause for the construct or any enclosing data construct will be treated as if it appeared in a copy clause for the kernels construct. If there is a default(present) clause on the construct, the compiler will implicitly treat all arrays and variables of aggregate data type without predetermined data attributes as if they appeared in a present clause. A scalar variable referenced in the kernels construct that does not appear in a data clause for the construct or any enclosing data construct will be treated as if it appeared in a copy clause.
Restrictions

- A program may not branch into or out of an OpenACC kernels construct.
- A program must not depend on the order of evaluation of the clauses, or on any side effects of the evaluations.
- Only the async, wait, num_gangs, num_workers, and vector_length clauses may follow a device_type clause.
- At most one if clause may appear. In Fortran, the condition must evaluate to a scalar logical value; in C or C++, the condition must evaluate to a scalar integer value.
- At most one default clause may appear, and it must have a value of either none or present.

The copy, copyin, copyout, create, no_create, present, deviceptr, and attach data clauses are described in Section 2.7 Data Clauses. The device_type clause is described in Section 2.4 Device-Specific Clauses.

2.5.3. Serial Construct

Summary  In C and C++, the syntax of the OpenACC serial construct is

```
#pragma acc serial [clause-list] new-line
structured block
```

and in Fortran, the syntax is

```
$acc serial [clause-list]
structured block
$acc end serial
```

where clause is one of the following:

- async [[ ( int-expr ) ]]
- wait [[ ( int-expr-list ) ]]
- device_type( device-type-list )
- if( condition )
- reduction( operator : var-list )
- copy( var-list )
- copyin( var-list )
- copyout( var-list )
- create( var-list )
- no_create( var-list )
- present( var-list )
- deviceptr( var-list )
- private( var-list )
- firstprivate( var-list )
- attach( var-list )
- default( none | present )
Description

When the program encounters an accelerator serial construct, one gang of one worker with a vector length of one is created to execute the accelerator serial region sequentially. The single gang begins executing the code in the structured block in gang-redundant mode, even though there is a single gang. The serial construct executes as if it were a parallel construct with clauses num_gangs(1) num_workers(1) vector_length(1).

If the async clause is not present, there is an implicit barrier at the end of the accelerator serial region, and the execution of the local thread will not proceed until the gang has reached the end of the serial region.

If there is no default(none) clause on the construct, the compiler will implicitly determine data attributes for variables that are referenced in the compute construct that do not have predetermined data attributes and do not appear in a data clause on the compute construct, a lexically containing data construct, or a visible declare directive. If there is no default(present) clause on the construct, an array or variable of aggregate data type referenced in the serial construct that does not appear in a data clause for the construct or any enclosing data construct will be treated as if it appeared in a copy clause for the serial construct. If there is a default(present) clause on the construct, the compiler will implicitly treat all arrays and variables of aggregate data type without predetermined data attributes as if they appeared in a present clause. A scalar variable referenced in the serial construct that does not appear in a data clause for the construct or any enclosing data construct will be treated as if it appeared in a firstprivate clause.

Restrictions

- A program may not branch into or out of an OpenACC serial construct.
- A program must not depend on the order of evaluation of the clauses, or on any side effects of the evaluations.
- Only the async and wait clauses may follow a device_type clause.
- At most one if clause may appear. In Fortran, the condition must evaluate to a scalar logical value; in C or C++, the condition must evaluate to a scalar integer value.
- At most one default clause may appear, and it must have a value of either none or present.

The copy, copyin, copyout, create, no_create, present, deviceptr, and attach data clauses are described in Section 2.7 Data Clauses. The private and firstprivate clauses are described in Sections 2.5.10 and Sections 2.5.11. The device_type clause is described in Section 2.4 Device-Specific Clauses.

2.5.4. if clause

The if clause is optional; when there is no if clause, the compiler will generate code to execute the region on the current accelerator device.

When an if clause appears, the compiler will generate two copies of the construct, one copy to execute on the accelerator and one copy to execute on the encountering local thread. When the condition evaluates to nonzero in C or C++, or .true. in Fortran, the accelerator copy will be executed. When the condition in the if clause evaluates to zero in C or C++, or .false. in Fortran, the encountering local thread will execute the construct.
The async clause is optional; see Section 2.16 Asynchronous Behavior for more information.

The wait clause is optional; see Section 2.16 Asynchronous Behavior for more information.

The num_gangs clause is allowed on the parallel and kernels constructs. The value of the integer expression defines the number of parallel gangs that will execute the parallel region, or that will execute each kernel created for the kernels region. If the clause is not specified, an implementation-defined default will be used; the default may depend on the code within the construct. The implementation may use a lower value than specified based on limitations imposed by the target architecture.

The num_workers clause is allowed on the parallel and kernels constructs. The value of the integer expression defines the number of workers within each gang that will be active after a gang transitions from worker-single mode to worker-partitioned mode. If the clause is not specified, an implementation-defined default will be used; the default may be 1, and may be different for each parallel construct or for each kernel created for a kernels construct. The implementation may use a different value than specified based on limitations imposed by the target architecture.

The vector_length clause is allowed on the parallel and kernels constructs. The value of the integer expression defines the number of vector lanes that will be active after a worker transitions from vector-single mode to vector-partitioned mode. This clause determines the vector length to use for vector or SIMD operations. If the clause is not specified, an implementation-defined default will be used. This vector length will be used for loops annotated with the vector clause on a loop directive, as well as loops automatically vectorized by the compiler. The implementation may use a different value than specified based on limitations imposed by the target architecture.

The private clause is allowed on the parallel and serial constructs; it declares that a copy of each item on the list will be created for each gang.

Restrictions
2.5.11. firstprivate clause

The `firstprivate` clause is allowed on the `parallel` and `serial` constructs; it declares that a copy of each item on the list will be created for each gang, and that the copy will be initialized with the value of that item on the encountering thread when a `parallel` or `serial` construct is encountered.

**Restrictions**

- See Section 2.17 [Fortran Optional Arguments] for discussion of Fortran optional arguments in `firstprivate` clauses.

2.5.12. reduction clause

The `reduction` clause is allowed on the `parallel` and `serial` constructs. It specifies a reduction operator and one or more scalar variables. For each variable, a private copy is created for each parallel gang and initialized for that operator. At the end of the region, the values for each gang are combined using the reduction operator, and the result combined with the value of the original variable and stored in the original variable. The reduction result is available after the region.

The following table lists the operators that are valid and the initialization values; in each case, the initialization value will be cast into the variable type. For `max` and `min` reductions, the initialization values are the least representable value and the largest representable value for the variable’s data type, respectively. Supported data types are the numerical data types in C (char, int, float, double, _Complex), C++ (char, wchar_t, int, float, double), and Fortran (integer, real, double precision, complex).

<table>
<thead>
<tr>
<th>C and C++</th>
<th>Fortran</th>
</tr>
</thead>
<tbody>
<tr>
<td>operator</td>
<td>initialization value</td>
</tr>
<tr>
<td>+</td>
<td>0</td>
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<td>*</td>
<td>1</td>
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<td>max</td>
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**Restrictions**

- See Section 2.17 [Fortran Optional Arguments] for discussion of Fortran optional arguments in `firstprivate` clauses.
The reduction variable may not be an array element.

The reduction variable may not be a C struct member, C++ class or struct member, or Fortran derived type member.

See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in reduction clauses.

2.5.13. default clause

The default clause is optional. The none argument tells the compiler to require that all arrays or variables used in the compute construct that do not have predetermined data attributes to explicitly appear in a data clause on the compute construct, a data construct that lexically contains the compute construct, or a visible declare directive. The present argument causes all arrays or variables of aggregate data type used in the compute construct that have implicitly determined data attributes to be treated as if they appeared in a present clause.

2.6. Data Environment

This section describes the data attributes for variables. The data attributes for a variable may be predetermined, implicitly determined, or explicitly determined. Variables with predetermined data attributes may not appear in a data clause that conflicts with that data attribute. Variables with implicitly determined data attributes may appear in a data clause that overrides the implicit attribute. Variables with explicitly determined data attributes are those which appear in a data clause on a data construct, a compute construct, or a declare directive.

OpenACC supports systems with accelerators that have distinct memory from the host as well as systems with accelerators that share memory with the host. In the former case, called a non-shared memory device, the system has separate host memory and device memory. In the latter case, called a shared memory device as the accelerator shares memory with the host thread, the system has one shared memory. When a nested OpenACC construct is executed on the device, the default target device for that construct is the same device on which the encountering accelerator thread is executing. In that case, the target device shares memory with the encountering thread.

2.6.1. Variables with Predetermined Data Attributes

The loop variable in a C for statement or Fortran do statement that is associated with a loop directive is predetermined to be private to each thread that will execute each iteration of the loop. Loop variables in Fortran do statements within a compute construct are predetermined to be private to the thread that executes the loop.

Variables declared in a C block that is executed in vector-partitioned mode are private to the thread associated with each vector lane. Variables declared in a C block that is executed in worker-partitioned vector-single mode are private to the worker and shared across the threads associated with the vector lanes of that worker. Variables declared in a C block that is executed in worker-single mode are private to the gang and shared across the threads associated with the workers and vector lanes of that gang.
A procedure called from a compute construct will be annotated as seq, vector, worker, or gang, as described Section [2.1.5] Procedure Calls in Compute Regions. Variables declared in seq routine are private to the thread that made the call. Variables declared in vector routine are private to the worker that made the call and shared across the threads associated with the vector lanes of that worker. Variables declared in worker or gang routine are private to the gang that made the call and shared across the threads associated with the workers and vector lanes of that gang.

2.6.2. Data Regions and Data Lifetimes

For a shared-memory device, data is accessible to the local thread and to the accelerator. Such data is available to the accelerator for the lifetime of the variable. For a non-shared memory device, data in host memory is allocated in device memory and copied between host and device memory by using data constructs, clauses, and API routines. A data lifetime is the duration from when the data is first made available to the accelerator until it becomes unavailable, after having been deallocated from device memory, for instance.

There are four types of data regions. When the program encounters a data construct, it creates a data region.

When the program encounters a compute construct with explicit data clauses or with implicit data allocation added by the compiler, it creates a data region that has a duration of the compute construct.

When the program enters a procedure, it creates an implicit data region that has a duration of the procedure. That is, the implicit data region is created when the procedure is called, and exited when the program returns from that procedure invocation. There is also an implicit data region associated with the execution of the program itself. The implicit program data region has a duration of the execution of the program.

In addition to data regions, a program may create and delete data on the accelerator using enter data and exit data directives or using runtime API routines. When the program executes an enter data directive, or executes a call to a runtime API acc_copyin or acc_create routine, each variable, array, or subarray on the directive or the variable on the runtime API argument list will be made live on accelerator.

2.6.3. Data Construct

**Summary**  The data construct defines scalars, arrays, and subarrays to be allocated in the current device memory for the duration of the region, whether data should be copied from the host to the device memory upon region entry, and copied from the device to host memory upon region exit.

**Syntax**  In C and C++, the syntax of the OpenACC data construct is

```
#pragma acc data [clause-list] new-line
structured block
```

and in Fortran, the syntax is

```
!$acc data [clause-list]
```
structured block

!$acc end data

where clause is one of the following:

if( condition )
copy( var-list )
copyin( var-list )
copyout( var-list )
create( var-list )
no_create( var-list )
present( var-list )
deviceptr( var-list )
attach( var-list )

**Description**  Data will be allocated in the memory of the current device and copied from the host or local memory to the device, or copied back, as required. The data clauses are described in Section 2.7 Data Clauses. Structured reference counts are incremented for data when entering a data region, and decremented when leaving the region, as described in Section 2.6.5 Reference Counting.

**if clause**

The if clause is optional; when there is no if clause, the compiler will generate code to allocate memory on the current accelerator device and move data from and to the local memory as required. When an if clause appears, the program will conditionally allocate memory on, and move data to and/or from the device. When the condition in the if clause evaluates to zero in C or C++, or .false. in Fortran, no device memory will be allocated, and no data will be moved. When the condition evaluates to nonzero in C or C++, or .true. in Fortran, the data will be allocated and moved as specified. At most one if clause may appear.

2.6.4. Enter Data and Exit Data Directives

**Summary**  An enter data directive may be used to define scalars, arrays and subarrays to be allocated in the current device memory for the remaining duration of the program, or until an exit data directive that deallocates the data. They also tell whether data should be copied from the host to the device memory at the enter data directive, and copied from the device to host memory at the exit data directive. The dynamic range of the program between the enter data directive and the matching exit data directive is the data lifetime for that data.

**Syntax**  In C and C++, the syntax of the OpenACC enter data directive is

```
#pragma acc enter data clause-list new-line
```

and in Fortran, the syntax is
The OpenACC® API 2.6. Data Environment

!$acc enter data clause-list

where clause is one of the following:

if( condition )
async [ [ int-expr ] ]
wait [ [ int-expr-list ] ]
copyin( var-list )
create( var-list )
attach( var-list )

In C and C++, the syntax of the OpenACC exit data directive is

#pragma acc exit data clause-list new-line

and in Fortran, the syntax is

!$acc exit data clause-list

where clause is one of the following:

if( condition )
async [ [ int-expr ] ]
wait [ [ int-expr-list ] ]
copyout( var-list )
detach( var-list )
finalize

Description At an enter data directive, data may be allocated in the current device memory and copied from the host or local memory to the device. This action enters a data lifetime for those variables, arrays, or subarrays, and will make the data available for present clauses on constructs within the data lifetime. Dynamic reference counts are incremented for this data, as described in Section 2.6.5 Reference Counting. Pointers in device memory may be attached to point to the corresponding device copy of the host pointer target.

At an exit data directive, data may be copied from the device memory to the host or local memory and deallocated from device memory. If no finalize clause appears, dynamic reference counts are decremented for this data. If a finalize clause appears, the dynamic reference counts are set to zero for this data. Pointers in device memory may be detached so as to have the same value as the corresponding host pointer.

The data clauses are described in Section 2.7 Data Clauses. Reference counting behavior is described in Section 2.6.5 Reference Counting.
The if clause

The if clause is optional; when there is no if clause, the compiler will generate code to allocate or deallocate memory on the current accelerator device and move data from and to the local memory. When an if clause appears, the program will conditionally allocate or deallocate device memory and move data to and/or from the device. When the condition in the if clause evaluates to zero in C or C++, or .false. in Fortran, no device memory will be allocated or deallocated, and no data will be moved. When the condition evaluates to nonzero in C or C++, or .true. in Fortran, the data will be allocated or deallocated and moved as specified.

async clause

The async clause is optional; see Section 2.16 Asynchronous Behavior for more information.

wait clause

The wait clause is optional; see Section 2.16 Asynchronous Behavior for more information.

finalize clause

The finalize clause is allowed on the exit data directive and is optional. When no finalize clause appears, the exit data directive will decrement the dynamic reference counts for variables and arrays appearing in copyout and delete clauses, and will decrement the attachment counts for pointers appearing in detach clauses. If a finalize clause appears, the exit data directive will set the dynamic reference counts to zero for variables and arrays appearing in copyout and delete clauses, and will set the attachment counts to zero for pointers appearing in detach clauses.

2.6.5. Reference Counting

When data is allocated on a non-shared memory device due to data clauses or OpenACC API routine calls, the OpenACC implementation keeps track of that device memory and its relationship to the corresponding data in host memory. Each section of device memory will be associated with two reference counts. A structured reference count is incremented when entering each data or compute region that contain an explicit data clause or implicitly-determined data attributes for that block of memory, and is decremented when exiting that region. A dynamic reference count is incremented for each enter data copyin or create clause, or each acc_copyin or acc_create API routine call for that block of memory. The dynamic reference count is decremented for each exit data copyout or delete clause when no finalize clause appears, or each acc_copyout or acc_delete API routine call for that block of memory. The dynamic reference count will be set to zero with an exit data copyout or delete clause when a finalize clause appears, or each acc_copyout_finalize or acc_delete_finalize API routine call for the block of memory. The reference counts are modified synchronously with the encountering thread, even if the data directives include an async clause. When both structured and dynamic reference counts reach zero, the data lifetime for that data ends.
2.6.6. Attachment Counters

This section describes the behavior when attaching pointer variables in device memory to pointer targets in device memory. A pointer may be a C or C++ pointer (e.g., float*), a Fortran pointer or array pointer (e.g., real, pointer, dimension(:)), or a Fortran allocatable (e.g., real, allocatable, dimension(:)).

When data is copied from host memory to device memory, the values are copied exactly. If the data is a pointer or a data structure that includes a pointer, the pointer value copied to device memory will be the host pointer value. If the pointer target is also allocated on or copied to the device, an attach action updates the pointer in device memory to point to the device copy of the data that the host pointer targets. For Fortran array pointers and allocatable arrays, this includes copying any associated descriptor (dope vector) to the device copy of the pointer. When the device pointer target is deallocated, the pointer in device memory should be restored to the host value, so it can be safely copied back to host memory. A detach action updates the pointer in device memory to have the same value as the corresponding pointer in local memory.

Since multiple pointers can target the same address, each pointer in device memory is associated with an attachment counter. The attachment counter for a pointer is initialized to zero when the pointer is allocated in device memory. The attachment counter for a pointer is set to one whenever the pointer is attached to new target address, and incremented whenever an attach action for that pointer is performed for the same target address. The attachment counter is decremented whenever a detach action occurs for the pointer, and the pointer is detached when the attachment counter reaches zero. This is described in more detail in Section 2.7.2 Data Clause Actions.

A pointer in device memory can be assigned a device address in two ways. The pointer can be attached to a device address due to data clauses or API routines, as described in Section 2.7.2 Data Clause Actions or the pointer can be assigned in a compute region on the device. Unspecified behavior may result if both ways are used for the same pointer.

Pointer members of structs, classes, or derived types in device or host memory can be overwritten due to update directives or API routines. It is the user’s responsibility to ensure that the pointers have the appropriate values before or after the data movement in either direction. The behavior of the program is undefined if any of the pointer members are attached when an update of an array or variable of aggregate data type is performed.

2.7. Data Clauses

These data clauses may appear on the parallel construct, kernels construct, serial construct, data construct, the enter data and exit data directives, and declare directives. In the descriptions, the region is a compute region with a clause appearing on a parallel, kernels, or serial construct, a data region with a clause on a data construct, or an implicit data region with a clause on a declare directive. If the declare directive appears in a global context, the corresponding implicit data region has a duration of the program. The list argument to each data clause is a comma-separated collection of variable names, array names, or subarray specifications. For all clauses except deviceptr and present, the list argument may include a Fortran common block name enclosed within slashes, if that common block name also appears in a declare directive link clause. In all cases, the compiler will allocate and manage a copy of the variable or array in the memory of the current device, creating a visible device copy of that variable.
or array, for non-shared memory devices.

OpenACC supports accelerators with physically and logically separate memories from the local thread. However, if the accelerator can access the local memory directly, the implementation may avoid the memory allocation and data movement and simply share the data in local memory. Therefore, a program that uses and assigns data on the host and uses and assigns the same data on the accelerator within a data region without update directives to manage the coherence of the two copies may get different answers on different accelerators or implementations.

Restrictions

- Data clauses may not follow a `device_type` clause.
- See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in data clauses.

### 2.7.1. Data Specification in Data Clauses

In C and C++, a subarray is an array name followed by an extended array range specification in brackets, with start and length, such as

```
AA[2:n]
```

If the lower bound is missing, zero is used. If the length is missing and the array has known size, the size of the array is used; otherwise the length is required. The subarray `AA[2:n]` means element `AA[2], AA[3], ..., AA[2+n-1].`

In C and C++, a two dimensional array may be declared in at least four ways:

- Statically-sized array: `float AA[100][200];`
- Pointer to statically sized rows: `typedef float row[200]; row* BB;`
- Statically-sized array of pointers: `float* CC[200];`
- Pointer to pointers: `float** DD;`

Each dimension may be statically sized, or a pointer to dynamically allocated memory. Each of these may be included in a data clause using subarray notation to specify a rectangular array:

```
AA[2:n][0:200]
BB[2:n][0:m]
CC[2:n][0:m]
DD[2:n][0:m]
```

Multidimensional rectangular subarrays in C and C++ may be specified for any array with any combination of statically-sized or dynamically-allocated dimensions. For statically sized dimensions, all dimensions except the first must specify the whole `extent`, to preserve the contiguous data restriction, discussed below. For dynamically allocated dimensions, the implementation will allocate pointers on the device corresponding to the pointers on the host, and will fill in those pointers as appropriate.
In Fortran, a subarray is an array name followed by a comma-separated list of range specifications in parentheses, with lower and upper bound subscripts, such as

\[ \text{arr}(1: \text{high}, \text{low}:100) \]

If either the lower or upper bounds are missing, the declared or allocated bounds of the array, if known, are used. All dimensions except the last must specify the whole extent, to preserve the contiguous data restriction, discussed below.

**Restrictions**

- In Fortran, the upper bound for the last dimension of an assumed-size dummy array must be specified.
- In C and C++, the length for dynamically allocated dimensions of an array must be explicitly specified.
- In C and C++, modifying pointers in pointer arrays during the data lifetime, either on the host or on the device, may result in undefined behavior.
- If a subarray is specified in a data clause, the implementation may choose to allocate memory for only that subarray on the accelerator.
- In Fortran, array pointers may be specified, but pointer association is not preserved in the device memory.
- Any array or subarray in a data clause, including Fortran array pointers, must be a contiguous block of memory, except for dynamic multidimensional C arrays.
- In C and C++, if a variable or array of struct or class type is specified, all the data members of the struct or class are allocated and copied, as appropriate. If a struct or class member is a pointer type, the data addressed by that pointer are not implicitly copied.
- In Fortran, if a variable or array with derived type is specified, all the members of that derived type are allocated and copied, as appropriate. If any member has the allocatable or pointer attribute, the data accessed through that member are not copied.
- If an expression is used in a subscript or subarray expression in a clause on a data construct, the same value is used when copying data at the end of the data region, even if the values of variables in the expression change during the data region.

**2.7.2. Data Clause Actions**

Most of the data clauses perform one or more the following actions. The actions test or modify one or both of the structured and dynamic reference counts, depending on the directive on which the data clause appears.

**Present Increment Action**

A present increment action is one of the actions that may be performed for a present (Section 2.7.4), copy (Section 2.7.5), copyin (Section 2.7.6), copyout (Section 2.7.7), create (Sec-
A present increment action for a `var` occurs only when `var` is already present on the device.

A present increment action for a `var` increments the structured or dynamic reference count for `var`.

### Present Decrement Action

A present decrement action is one of the actions that may be performed for a **present** (Section 2.7.4), **copy** (Section 2.7.5), **copyin** (Section 2.7.6), **copyout** (Section 2.7.7), **create** (Section 2.7.8), **no_create** (Section 2.7.9), or **delete** (Section 2.7.10) clause, or for a call to an `acc_copyout` (Section 3.2.22) or `acc_delete` (Section 3.2.23) API routine. See those sections for details.

A present decrement action for a `var` occurs only when `var` is already present on the device.

A present decrement action for a `var` decrements the structured or dynamic reference count for `var`, if its value is greater than zero. If the reference count is already zero, its value is left unchanged.

### Create Action

A create action is one of the actions that may be performed for a **copyout** (Section 2.7.7) or **create** (Section 2.7.8) clause, or for a call to an `acc_create` API routine (Section 3.2.21). See those sections for details.

A create action for a `var` occurs only when `var` is not already present on the device.

A create action for a `var`:

- allocates device memory for `var`; and
- sets the structured or dynamic reference count to one.

### Copyin Action

A copyin action is one of the actions that may be performed for a **copy** (Section 2.7.5) or **copyin** (Section 2.7.6) clause, or for a call to an `acc_copyin` API routine (Section 3.2.20). See those sections for details.

A copyin action for a `var` occurs only when `var` is not already present on the device.

A copyin action for a `var`:

- allocates device memory for `var`;
- initiates a copy of the data for `var` from the local thread memory to the corresponding device memory; and
- sets the structured or dynamic reference count to one.

The data copy may complete asynchronously, depending on other clauses on the directive.
Copyout Action

A *copyout* action is one of the actions that may be performed for a *copy* (Section 2.7.5) or *copyout* (Section 2.7.7) clause, or for a call to an *acc_copyout* API routine (Section 3.2.22). See those sections for details.

A *copyout* action for a *var* occurs only when *var* is present on the device.

A *copyout* action for a *var*:
- performs an *immediate detach* action for any pointer in *var*;
- initiates a copy of the data for *var* from the device memory to the corresponding local thread memory; and
- deallocates the device memory for *var*.

The data copy may complete asynchronously, depending on other clauses on the directive, in which case the memory is deallocated when the data copy is complete.

Delete Action

A *present decrement* action is one of the actions that may be performed for a *present* (Section 2.7.4), *copyin* (Section 2.7.6), *create* (Section 2.7.8), *no_create* (Section 2.7.9), or *delete* (Section 2.7.10) clause, or for a call to an *acc_delete* API routine (Section 3.2.23). See those sections for details.

A *delete* action for a *var* occurs only when *var* is present on the device.

A *delete* action for *var*:
- performs an *immediate detach* action for any pointer in *var*; and
- deallocates device memory for *var*.

Attach Action

An *attach* action is one of the actions that may be performed for a *present* (Section 2.7.4), *copy* (Section 2.7.5), *copyin* (Section 2.7.6), *copyout* (Section 2.7.7), *create* (Section 2.7.8), *no_create* (Section 2.7.9), or *attach* (Section 2.7.10) clause, or for a call to an *acc_attach* API routine (Section 3.2.34). See those sections for details.

An *attach* action for a *var* occurs only when *var* is a pointer reference.

If the current device is a shared memory device or if the pointer *var* is not present on the device, or if the address to which *var* points is not present on the device, no action is taken. If the *attachment counter* for *var* is nonzero and the pointer in device memory already points to the device copy of the data in *var*, the *attachment counter* for the pointer *var* is incremented. Otherwise, the pointer in device memory is *attached* to the device copy of the data by initiating an update for the pointer in device memory to point to the device copy of the data and setting the *attachment counter* for the pointer *var* to one. The update may complete asynchronously, depending on other clauses on the directive. The pointer update must follow any data copies due to *copyin* actions that are performed for the same directive.
Detach Action

A detach action is one of the actions that may be performed for a present (Section 2.7.4), copy (Section 2.7.5), copyin (Section 2.7.6), copyout (Section 2.7.7), create (Section 2.7.8), no_create (Section 2.7.9), delete (Section 2.7.10), or detach (Section 2.7.10) clause, or for a call to an acc_detach API routine (Section 3.2.35). See those sections for details.

A detach action for a var occurs only when var is a pointer reference.

If the current device is a shared memory device, or if var is not present on the device, or if the attachment counter for var for the pointer is zero, no action is taken. Otherwise, the attachment counter for the pointer var is decremented. If the attachment counter is decreased to zero, the pointer is detached by initiating an update for the pointer var in device memory to have the same value as the corresponding pointer in local memory. The update may complete asynchronously, depending on other clauses on the directive. The pointer update must precede any data copies due to copyout actions that are performed for the same directive.

Immediate Detach Action

An immediate detach action is one of the actions that may be performed for a detach (Section 2.7.10) clause, or for a call to an acc_detach_finalize API routine (Section 3.2.35). See those sections for details.

An immediate detach action for a var occurs only when var is a pointer reference and is present on the device.

If the attachment counter for the pointer is zero, the immediate detach action has no effect. Otherwise, the attachment counter for the pointer set to zero and the pointer is detached by initiating an update for the pointer in device memory to have the same value as the corresponding pointer in local memory. The update may complete asynchronously, depending on other clauses on the directive. The pointer update must precede any data copies due to copyout actions that are performed for the same directive.

2.7.3. deviceptr clause

The deviceptr clause may appear on structured data and compute constructs and declare directives.

The deviceptr clause is used to declare that the pointers in var-list are device pointers, so the data need not be allocated or moved between the host and device for this pointer.

In C and C++, the variables in var-list must be pointer variables.

In Fortran, the variables in var-list must be dummy arguments (arrays or scalars), and may not have the Fortran pointer, allocatable, or value attributes.

For a shared-memory device, host pointers are the same as device pointers, so this clause has no effect.
2.7.4. present clause

The present clause may appear on structured data and compute constructs and declare directives. If the current device is a shared memory device, no action is taken.

For a non-shared memory device, the present clause specifies that variables or arrays in var-list are already present in device memory on the current device due to data regions or data lifetimes that contain the construct on which the present clause appears.

If the current device is a non-shared memory device, the present clause behaves as follows, for each var in var-list.

- At entry to the region:
  - If var is not present on the current device, a runtime error is issued.
  - Otherwise, a present increment action with the structured reference count is performed. If var is a pointer reference, an attach action is performed.

- At exit from the region:
  - If var is not present on the current device, a runtime error is issued.
  - Otherwise, a present decrement action with the structured reference count is performed. If var is a pointer reference, a detach action is performed. If both structured and dynamic reference counts are zero, a delete action is performed.

Restrictions

- If only a subarray of an array is present on the current device, the present clause must specify the same subarray, or a subarray that is a proper subset of the subarray in the data lifetime.
- It is a runtime error if the subarray in var-list clause includes array elements that are not part of the subarray specified in the data lifetime.

2.7.5. copy clause

The copy clause may appear on structured data and compute constructs and on declare directives. If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the copy clause behaves as follows, for each var in var-list.

- At entry to the region:
  - If var is present, a present increment action with the structured reference count is performed. If var is a pointer reference, an attach action is performed.
  - Otherwise, a copyin action with the structured reference count is performed. If var is a pointer reference, an attach action is performed.

- At exit from the region:
  - If var is not present on the current device, a runtime error is issued.
Otherwise, a \texttt{present decrement} action with the structured reference count is performed. If \texttt{var} is a pointer reference, a \texttt{detach} action is performed. If both structured and dynamic reference counts are zero, a \texttt{copyout} action is performed.

The restrictions regarding subarrays in the \texttt{present} clause apply to this clause.

For compatibility with OpenACC 2.0, \texttt{present\_or\_copy} and \texttt{pcopy} are alternate names for \texttt{copy}.

### 2.7.6. copyin clause

The \texttt{copyin} clause may appear on structured \texttt{data} and compute constructs, on \texttt{declare} directives, and on \texttt{enter data} directives. If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the \texttt{copyin} clause behaves as follows, for each \texttt{var} in \texttt{var-list}:

- At entry to a region, the structured reference count is used. On an \texttt{enter data} directive, the dynamic reference count is used.
  - If \texttt{var} is present, a \texttt{present increment} action with the appropriate reference count is performed. If \texttt{var} is a pointer reference, an \texttt{attach} action is performed.
  - Otherwise, a \texttt{copyin} action with the appropriate reference count is performed. If \texttt{var} is a pointer reference, an \texttt{attach} action is performed.

- At exit from the region:
  - If \texttt{var} is not present on the current device, a runtime error is issued.
  - Otherwise, a \texttt{present decrement} action with the structured reference count is performed. If \texttt{var} is a pointer reference, a \texttt{detach} action is performed. If both structured and dynamic reference counts are zero, a \texttt{delete} action is performed.

The restrictions regarding subarrays in the \texttt{present} clause apply to this clause.

For compatibility with OpenACC 2.0, \texttt{present\_or\_copyin} and \texttt{pcopyin} are alternate names for \texttt{copyin}.

An \texttt{enter data} directive with a \texttt{copyin} clause is functionally equivalent to a call to the \texttt{acc_copyin} API routine, as described in Section 3.2.20.

### 2.7.7. copyout clause

The \texttt{copyout} clause may appear on structured \texttt{data} and compute constructs, on \texttt{declare} directives, and on \texttt{exit data} directives. If the current device is a shared memory device, no action is performed.

If the current device is a non-shared memory device, the \texttt{copyout} clause behaves as follows, for each \texttt{var} in \texttt{var-list}:

- At entry to a region:
  - If \texttt{var} is present, a \texttt{present increment} action with the structured reference count is per-
formed. If \textit{var} is a pointer reference, an \texttt{attach} action is performed.

- Otherwise, a \texttt{create} action with the structured reference is performed. If \textit{var} is a pointer reference, an \texttt{attach} action is performed.

- At exit from a region, the structured reference count is used. On an \texttt{exit data} directive, the dynamic reference count is used.

- If \textit{var} is not present on the current device, a runtime error is issued.

- Otherwise, the reference count is updated:
  
  * On an \texttt{exit data} directive with a \texttt{finalize} clause, the dynamic reference count is set to zero.
  
  * Otherwise, a \texttt{present decrement} action with the appropriate reference count is performed.

  If \textit{var} is a pointer reference, a \texttt{detach} action is performed. If both structured and dynamic reference counts are zero, a \texttt{delete} action is performed.

The restrictions regarding subarrays in the \texttt{present} clause apply to this clause.

For compatibility with OpenACC 2.0, \texttt{present or copyout} and \texttt{pcopyout} are alternate names for \texttt{copyout}.

An \texttt{exit data} directive with a \texttt{copyout} clause and with or without a \texttt{finalize} clause is functionally equivalent to a call to the \texttt{acc_copyout_final} or \texttt{acc_copyout} API routine, respectively, as described in Section 3.2.22.

2.7.8. create clause

The \texttt{create} clause may appear on structured \texttt{data} and compute constructs, on \texttt{declare} directives, and on \texttt{enter data} directives. If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the \texttt{create} clause behaves as follows, for each \textit{var} in \texttt{var-list}:

- At entry to a region, the structured reference count is used. On an \texttt{enter data} directive, the dynamic reference count is used.

  - If \textit{var} is present, a \texttt{present increment} action with the appropriate reference count is performed. If \textit{var} is a pointer reference, an \texttt{attach} action is performed.

  - Otherwise, a \texttt{create} action with the appropriate reference count is performed. If \textit{var} is a pointer reference, an \texttt{attach} action is performed.

- At exit from the region:

  - If \textit{var} is not present on the current device, a runtime error is issued.

  - Otherwise, a \texttt{present decrement} action with the structured reference count is performed. If \textit{var} is a pointer reference, a \texttt{detach} action is performed. If both structured and dynamic reference counts are zero, a \texttt{delete} action is performed.

The restrictions regarding subarrays in the \texttt{present} clause apply to this clause.
For compatibility with OpenACC 2.0, `present_or_create` and `pcreate` are alternate names for `create`.

An `enter data` directive with a `create` clause is functionally equivalent to a call to the `acc_create` API routine, as described in Section 3.2.21.

### 2.7.9. no_create clause

The `no_create` clause may appear on structured `data` and compute constructs. If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the `no_create` clause behaves as follows, for each `var` in `var-list`:

- At entry to the region:
  - If `var` is present, a `present increment` action with the structured reference count is performed. If `var` is a pointer reference, an `attach` action is performed.
  - Otherwise, no action is performed, and any device code in this construct will use the local memory address for `var`.

- At exit from the region:
  - If `var` is not present on the current device, no action is performed.
  - Otherwise, a `present decrement` action with the structured reference count is performed. If `var` is a pointer reference, a `detach` action is performed. If both structured and dynamic reference counts are zero, a `delete` action is performed.

The restrictions regarding subarrays in the `present` clause apply to this clause.

### 2.7.10. delete clause

The `delete` clause may appear on `exit data` directives. If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the `delete` clause behaves as follows, for each `var` in `var-list`:

- If `var` is not present on the current device, a runtime error is issued.

- Otherwise, the dynamic reference count is updated:
  - On an `exit data` directive with a `finalize` clause, the dynamic reference count is set to zero.
  - Otherwise, a `present decrement` action with the dynamic reference count is performed.

  If `var` is a pointer reference, a `detach` action is performed. If both structured and dynamic reference counts are zero, a `delete` action is performed.

An `exit data` directive with a `delete` clause and with or without a `finalize` clause is functionally equivalent to a call to the `acc_delete_finalized` or `acc_delete` API routine, respectively, as described in Section 3.2.23.
2.7.11. attach clause

The attach clause may appear on structured data and compute constructs and on enter data directives. If the current device is a shared memory device, no action is taken. Each var argument to an attach clause must be a C or C++ pointer or a Fortran variable or array with the pointer or allocatable attribute.

If the current device is a non-shared memory device, the attach clause behaves as follows, for each var in var-list:

- At entry to a region or at an enter data directive, an attach action is performed.
- At exit from the region, a detach action is performed.

2.7.12. detach clause

The detach clause may appear on exit data directives. If the current device is a shared memory device, no action is taken. Each var argument to a detach clause must be a C or C++ pointer or a Fortran variable or array with the pointer or allocatable attribute.

If the current device is a non-shared memory device, the detach clause behaves as follows, for each var in var-list: If the current device is a non-shared memory device,

- If there is a finalize clause on the exit data directive, an immediate detach action is performed.
- Otherwise, a detach action is performed.

2.8. Host_Data Construct

Summary  The host_data construct makes the address of device data available on the host.

Syntax  In C and C++, the syntax of the OpenACC host_data construct is

```
#pragma acc host_data clause-list new-line structured block
```

and in Fortran, the syntax is

```
!$acc host_data clause-list
structured block
!$acc end host_data
```

where clause is one of the following:

```
use_device( var-list )
if( condition )
if_present
```
Description  This construct is used to make the device address of data available in host code.

Restrictions

- At most one if clause may appear. In Fortran, the condition must evaluate to a scalar logical value; in C or C++, the condition must evaluate to a scalar integer value.
- See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in use_device clauses.

2.8.1. use_device clause

The use_device clause tells the compiler to use the current device address of any variable or array in var-list in code within the construct. In particular, this may be used to pass the device address of variables or arrays to optimized procedures written in a lower-level API. When there is no if_present clause, and either there is no if clause or the condition in the if clause evaluates to nonzero (in C or C++) or .true. (in Fortran), the variables or arrays in var-list must be present in the accelerator memory due to data regions or data lifetimes that contain this construct. On a shared memory accelerator, the device address may be the same as the host address.

2.8.2. if clause

The if clause is optional. When an if clause appears and the condition evaluates to zero in C or C++, or .false. in Fortran, the compiler will not change the addresses of any variable or array in code within the construct. When there is no if clause, or when an if clause appears and the condition evaluates to nonzero in C or C++, or .true. in Fortran, the compiler will replace the addresses as described in the previous subsection.

2.8.3. if_present clause

When an if_present clause appears on the directive, the compiler will only change the address of any variable or array which appears in var-list that is present on the current device.

2.9. Loop Construct

Summary  The OpenACC loop construct applies to a loop which must immediately follow this directive. The loop construct can describe what type of parallelism to use to execute the loop and declare private variables and arrays and reduction operations.

Syntax  In C and C++, the syntax of the loop construct is

```
#pragma acc loop [clause-list] new-line
for loop
```

In Fortran, the syntax of the loop construct is
!$acc loop [clause-list]
do loop

where clause is one of the following:

collapse( n )
gang [ [ gang-arg-list ] ]
seq
auto
tile( size-expr-list )
device_type( device-type-list )
independent
private( var-list )
reduction( operator: var-list )

where gang-arg is one of:

[ [num: ]int-expr
static: size-expr

and gang-arg-list may have at most one num and one static argument,
and where size-expr is one of:

* int-expr

Some clauses are only valid in the context of a kernels construct; see the descriptions below.

An orphaned loop construct is a loop construct that is not lexically enclosed within a compute construct. The parent compute construct of a loop construct is the nearest compute construct that lexically contains the loop construct.

Restrictions

- Only the collapse, gang, worker, vector, seq, auto, and tile clauses may follow a device_type clause.
- The int-expr argument to the worker and vector clauses must be invariant in the kernels region.
- A loop associated with a loop construct that does not have a seq clause must be written such that the loop iteration count is computable when entering the loop construct.
The collapse clause

The collapse clause is used to specify how many tightly nested loops are associated with the loop construct. The argument to the collapse clause must be a constant positive integer expression. If no collapse clause is present, only the immediately following loop is associated with the loop construct.

If more than one loop is associated with the loop construct, the iterations of all the associated loops are all scheduled according to the rest of the clauses. The trip count for all loops associated with the collapse clause must be computable and invariant in all the loops.

It is implementation-defined whether a gang, worker or vector clause on the construct is applied to each loop, or to the linearized iteration space.

The gang clause

When the parent compute construct is a parallel construct, or on an orphaned loop construct, the gang clause specifies that the iterations of the associated loop or loops are to be executed in parallel by distributing the iterations among the gangs created by the parallel construct. A loop construct with the gang clause transitions a compute region from gang-redundant mode to gang-partitioned mode. The number of gangs is controlled by the parallel construct; only the static argument is allowed. The loop iterations must be data independent, except for variables specified in a reduction clause. The region of a loop with the gang clause may not contain another loop with the gang clause unless within a nested compute region.

When the parent compute construct is a kernels construct, the gang clause specifies that the iterations of the associated loop or loops are to be executed in parallel across the gangs. An argument with no keyword or with the num keyword is allowed only when the num_gangs does not appear on the kernels construct. If an argument with no keyword or an argument after the num keyword is specified, it specifies how many gangs to use to execute the iterations of this loop. The region of a loop with the gang clause may not contain another loop with a gang clause unless within a nested compute region.

The scheduling of loop iterations to gangs is not specified unless the static argument appears as an argument. If the static argument appears with an integer expression, that expression is used as a chunk size. If the static argument appears with an asterisk, the implementation will select a chunk size. The iterations are divided into chunks of the selected chunk size, and the chunks are assigned to gangs starting with gang zero and continuing in round-robin fashion. Two gang loops in the same parallel region with the same number of iterations, and with static clauses with the same argument, will assign the iterations to gangs in the same manner. Two gang loops in the same kernels region with the same number of iterations, the same number of gangs to use, and with static clauses with the same argument, will assign the iterations to gangs in the same manner.

The worker clause

When the parent compute construct is a parallel construct, or on an orphaned loop construct, the worker clause specifies that the iterations of the associated loop or loops are to be executed in parallel by distributing the iterations among the multiple workers within a single gang. A loop construct with a worker clause causes a gang to transition from worker-single mode to worker-
partitioned mode. In contrast to the gang clause, the worker clause first activates additional worker-level parallelism and then distributes the loop iterations across those workers. No argument is allowed. The loop iterations must be data independent, except for variables specified in a reduction clause. The region of a loop with the worker clause may not contain a loop with the gang or worker clause unless within a nested compute region.

When the parent compute construct is a kernels construct, the worker clause specifies that the iterations of the associated loop or loops are to be executed in parallel across the workers within a single gang. An argument is allowed only when the num_workers does not appear on the kernels construct. The optional argument specifies how many workers per gang to use to execute the iterations of this loop. The region of a loop with the worker clause may not contain a loop with a gang or worker clause unless within a nested compute region.

All workers will complete execution of their assigned iterations before any worker proceeds beyond the end of the loop.

2.9.4. vector clause

When the parent compute construct is a parallel construct, or on an orphaned loop construct, the vector clause specifies that the iterations of the associated loop or loops are to be executed in vector or SIMD mode. A loop construct with a vector clause causes a worker to transition from vector-single mode to vector-partitioned mode. Similar to the worker clause, the vector clause first activates additional vector-level parallelism and then distributes the loop iterations across those vector lanes. The operations will execute using vectors of the length specified or chosen for the parallel region. The region of a loop with the vector clause may not contain a loop with the gang, worker, or vector clause unless within a nested compute region.

When the parent compute construct is a kernels construct, the vector clause specifies that the iterations of the associated loop or loops are to be executed with vector or SIMD processing. An argument is allowed only when the vector_length does not appear on the kernels construct. If an argument is specified, the iterations will be processed in vector strips of that length; if no argument is specified, the implementation will choose an appropriate vector length. The region of a loop with the vector clause may not contain a loop with a gang, worker, or vector clause unless within a nested compute region.

All vector lanes will complete execution of their assigned iterations before any vector lane proceeds beyond the end of the loop.

2.9.5. seq clause

The seq clause specifies that the associated loop or loops are to be executed sequentially by the accelerator. This clause will override any automatic parallelization or vectorization.

2.9.6. auto clause

The auto clause specifies that the implementation must analyze the loop and determine whether the loop iterations are data independent and, if so, select whether to apply parallelism to this loop or whether to run the loop sequentially. The implementation may be restricted to the types of
parallelism it can apply by the presence of loop constructs with gang, worker, or vector clauses for outer or inner loops. When the parent compute construct is a kernels construct, a loop construct with no independent or seq clause is treated as if it has the auto clause.

2.9.7. tile clause

The tile clause specifies that the implementation should split each loop in the loop nest into two loops, with an outer set of tile loops and an inner set of element loops. The argument to the tile clause is a list of one or more tile sizes, where each tile size is a constant positive integer expression or an asterisk. If there are \( n \) tile sizes in the list, the loop construct must be immediately followed by \( n \) tightly-nested loops. The first argument in the size-expr-list corresponds to the innermost loop of the \( n \) associated loops, and the last element corresponds to the outermost associated loop. If the tile size is specified with an asterisk, the implementation will choose an appropriate value. Each loop in the nest will be split or strip-mined into two loops, an outer tile loop and an inner element loop. The trip count of the element loop will be limited to the corresponding tile size from the size-expr-list. The tile loops will be reordered to be outside all the element loops, and the element loops will all be inside the tile loops.

If the vector clause appears on the loop construct, the vector clause is applied to the element loops. If the gang clause appears on the loop construct, the gang clause is applied to the tile loops. If the worker clause appears on the loop construct, the worker clause is applied to the element loops if no vector clause appears, and to the tile loops otherwise.

2.9.8. device_type clause

The device_type clause is described in Section 2.4 Device-Specific Clauses.

2.9.9. independent clause

The independent clause tells the implementation that the iterations of this loop are data-independent with respect to each other. This allows the implementation to generate code to execute the iterations in parallel with no synchronization. When the parent compute construct is a parallel construct, the independent clause is implied on all loop constructs without a seq or auto clause.

Note

- It is likely a programming error to use the independent clause on a loop if any iteration writes to a variable or array element that any other iteration also writes or reads, except for variables in a reduction clause or accesses in atomic regions.

2.9.10. private clause

The private clause on a loop construct specifies that a copy of each item in var-list will be created. If the body of the loop is executed in vector-partitioned mode, a copy of the item is created for each thread associated with each vector lane. If the body of the loop is executed in worker-partitioned vector-single mode, a copy of the item is created for and shared across the set of threads.
associated with all the vector lanes of each worker. Otherwise, a copy of the item is created for and
shared across the set of threads associated with all the vector lanes of all the workers of each gang.

Restrictions
• See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in
private clauses.

2.9.11. reduction clause
The reduction clause specifies a reduction operator and one or more scalar variables. For each
reduction variable, a private copy is created in the same manner as for a private clause on the
loop construct, and initialized for that operator; see the table in Section 2.5.12 reduction clause. At
the end of the loop, the values for each thread are combined using the specified reduction operator,
and the result combined with the value of the original variable and stored in the original variable at
the end of the parallel or kernels region if the loop has gang parallelism, and at the end of the loop
otherwise.

In a parallel region, if the reduction clause is used on a loop with the vector or worker
classes (and no gang clause), and the scalar variable also appears in a private clause on the
parallel construct, the value of the private copy of the scalar will be updated at the exit of the
loop. If the scalar variable does not appear in a private clause on the parallel construct, or if
the reduction clause is used on a loop with the gang clause, the value of the scalar will not be
updated until the end of the parallel region.

If a variable is involved in a reduction that spans multiple nested loops where two or more of those
loops have associated loop directives, a reduction clause containing that variable must appear
on each of those loop directives.

Restrictions
• The reduction clause may not be specified on an orphaned loop construct with the gang
clause, or on an orphaned loop construct that will generate gang parallelism in a procedure
that is compiled with the routine gang clause.
• The restrictions for a reduction clause on a compute construct listed in in Section 2.5.12
reduction clause also apply to a reduction clause on a loop construct.
• See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in
reduction clauses.

2.10. Cache Directive
Summary The cache directive may appear at the top of (inside of) a loop. It specifies array
elements or subarrays that should be fetched into the highest level of the cache for the body of the
loop.

Syntax In C and C++, the syntax of the cache directive is
In Fortran, the syntax of the cache directive is

```fortran
!$acc cache( var-list )
```

The entries in `var-list` must be single array elements or simple subarrays. In C and C++, a simple subarray is an array name followed by an extended array range specification in brackets, with start and length, such as

```c
arr[lower:length]
```

where the lower bound is a constant, loop invariant, or the `for` loop index variable plus or minus a constant or loop invariant, and the length is a constant.

In Fortran, a simple subarray is an array name followed by a comma-separated list of range specifications in parentheses, with lower and upper bound subscripts, such as

```fortran
arr(lower:upper, lower2:upper2)
```

The lower bounds must be constant, loop invariant, or the `do` loop index variable plus or minus a constant or loop invariant; moreover the difference between the corresponding upper and lower bounds must be a constant.

**Restrictions**
- If an array is listed in a `cache` directive, all references to that array during execution of that loop iteration must not refer to elements of the array outside the index range specified in the `cache` directive.
- See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in `cache` directives.

### 2.11. Combined Constructs

**Summary** The combined OpenACC `parallel loop`, `kernels loop`, and `serial loop` constructs are shortcuts for specifying a `loop` construct nested immediately inside a `parallel`, `kernels`, or `serial` construct. The meaning is identical to explicitly specifying a `parallel`, `kernels`, or `serial` construct containing a `loop` construct. Any clause that is allowed on a `parallel` or `loop` construct is allowed on the `parallel loop` construct; any clause allowed on a `kernels` or `loop` construct is allowed on a `kernels loop` construct; and any clause allowed on a `serial` or `loop` construct is allowed on a `serial loop` construct.
Syntax  In C and C++, the syntax of the \texttt{parallel loop} construct is

\begin{verbatim}
#pragma acc parallel loop [clause-list] new-line
  for loop
\end{verbatim}

In Fortran, the syntax of the \texttt{parallel loop} construct is

\begin{verbatim}
!$acc parallel loop [clause-list]
  do loop
  !$acc end parallel loop
\end{verbatim}

The associated structured block is the loop which must immediately follow the directive. Any of the \texttt{parallel} or \texttt{loop} clauses valid in a parallel region may appear. The \texttt{private} and \texttt{reduction} clauses, which can appear on both a \texttt{parallel} construct and a \texttt{loop} construct, are treated on a \texttt{parallel loop} construct as if they appeared on the \texttt{loop} construct.

In C and C++, the syntax of the \texttt{kernels loop} construct is

\begin{verbatim}
#pragma acc kernels loop [clause-list] new-line
  for loop
\end{verbatim}

In Fortran, the syntax of the \texttt{kernels loop} construct is

\begin{verbatim}
!$acc kernels loop [clause-list]
  do loop
  !$acc end kernels loop
\end{verbatim}

The associated structured block is the loop which must immediately follow the directive. Any of the \texttt{kernels} or \texttt{loop} clauses valid in a kernels region may appear.

In C and C++, the syntax of the \texttt{serial loop} construct is

\begin{verbatim}
#pragma acc serial loop [clause-list] new-line
  for loop
\end{verbatim}

In Fortran, the syntax of the \texttt{serial loop} construct is

\begin{verbatim}
!$acc serial loop [clause-list]
  do loop
  !$acc end serial loop
\end{verbatim}

The associated structured block is the loop which must immediately follow the directive. Any of the \texttt{serial} or \texttt{loop} clauses valid in a serial region may appear. The \texttt{private} clause, which can appear on both a \texttt{serial} construct and a \texttt{loop} construct, is treated on a \texttt{serial loop} construct as if it appeared on the \texttt{loop} construct.
Restrictions

- The restrictions for the parallel, kernels, serial, and loop constructs apply.

2.12. Atomic Construct

Summary  An atomic construct ensures that a specific storage location is accessed and/or updated atomically, preventing simultaneous reading and writing by gangs, workers, and vector threads that could result in indeterminate values.

Syntax  In C and C++, the syntax of the atomic constructs is:

```
#pragma acc atomic [atomic-clause] new-line
expression-stmt
```

or:

```
#pragma acc atomic update capture new-line
structured-block
```

Where atomic-clause is one of read, write, update, or capture. The expression-stmt is an expression statement with one of the following forms:

If the atomic-clause is read:

```
v = x;
```

If the atomic-clause is write:

```
x = expr;
```

If the atomic-clause is update or not present:

```
x++;  
x--;  
++x;  
--x;  
x binop= expr;  
x = x binop expr;  
x = expr binop x;
```

If the atomic-clause is capture:

```
v = x++;  
v = x--;  
v = ++x;
```
The OpenACC API 2.12. Atomic Construct

\[
v = \texttt{x};
\]
\[
v = \texttt{x} \ \texttt{binop=} \ \texttt{expr};
\]
\[
v = \texttt{x} = \texttt{x} \ \texttt{binop} \ \texttt{expr};
\]
\[
v = \texttt{x} = \texttt{expr} \ \texttt{binop} \ \texttt{x};
\]

The \textit{structured-block} is a structured block with one of the following forms:

\[
\{v = x; \ x \ \texttt{binop=} \ \texttt{expr}; \}
\]
\[
\{x \ \texttt{binop=} \ \texttt{expr}; \ v = x; \}
\]
\[
\{v = x; \ x = x \ \texttt{binop} \ \texttt{expr}; \}
\]
\[
\{v = x; \ x = \texttt{expr} \ \texttt{binop} \ x; \}
\]
\[
\{x = \texttt{expr} \ \texttt{binop} \ x; \ v = x; \}
\]
\[
\{v = x; \ x = \texttt{expr}; \}
\]
\[
\{v = x; \ x++; \}
\]
\[
\{++x; \ v = x; \}
\]
\[
\{x++; \ v = x; \}
\]
\[
\{v = x; \ x--; \}
\]
\[
\{v = x; \ --x; \}
\]
\[
\{--x; \ v = x; \}
\]
\[
\{x--; \ v = x; \}
\]

In the preceding expressions:

- \texttt{x} and \texttt{v} (as applicable) are both l-value expressions with scalar type.
- During the execution of an atomic region, multiple syntactic occurrences of \texttt{x} must designate the same storage location.
- Neither of \texttt{v} and \texttt{expr} (as applicable) may access the storage location designated by \texttt{x}.
- Neither of \texttt{x} and \texttt{expr} (as applicable) may access the storage location designated by \texttt{v}.
- \texttt{expr} is an expression with scalar type.
- \texttt{binop} is one of \texttt{+, *, -, /, &, ^, |, <<, or >>}.
- \texttt{binop, binop=} is one of \texttt{++, and --} are not overloaded operators.
- The expression \texttt{x binop expr} must be mathematically equivalent to \texttt{x binop (expr)}. This requirement is satisfied if the operators in \texttt{expr} have precedence greater than \texttt{binop}, or by using parentheses around \texttt{expr} or subexpressions of \texttt{expr}.
- The expression \texttt{expr binop x} must be mathematically equivalent to \texttt{(expr) binop x}. This requirement is satisfied if the operators in \texttt{expr} have precedence equal to or greater than \texttt{binop}, or by using parentheses around \texttt{expr} or subexpressions of \texttt{expr}.
- For forms that allow multiple occurrences of \texttt{x}, the number of times that \texttt{x} is evaluated is unspecified.

In Fortran the syntax of the \texttt{atomic} constructs is:

```fortran
!$acc atomic read
```
capture-statement

[$\texttt{!}\$\text{acc end atomic}$]

or

$\texttt{!}\$\text{acc atomic write}

write-statement

[$\texttt{!}\$\text{acc end atomic}$]

or

$\texttt{!}\$\text{acc atomic [update]}

update-statement

[$\texttt{!}\$\text{acc end atomic}$]

or

$\texttt{!}\$\text{acc atomic capture}

update-statement
capture-statement

$\texttt{!}\$\text{acc end atomic}$

or

$\texttt{!}\$\text{acc atomic capture}
capture-statement

update-statement

$\texttt{!}\$\text{acc end atomic}$

or

$\texttt{!}\$\text{acc atomic capture}
capture-statement

write-statement

$\texttt{!}\$\text{acc end atomic}$

where write-statement has the following form (if atomic-clause is write or capture):

\[ x = \text{expr} \]

where capture-statement has the following form (if atomic-clause is capture or read):

\[ v = x \]
and where update-statement has one of the following forms (if atomic-clause is update, capture, or not present):

\[
\begin{align*}
\mathbf{x} &= \mathbf{x} \text{ operator } \text{expr} \\
\mathbf{x} &= \text{expr} \text{ operator } \mathbf{x} \\
\mathbf{x} &= \text{intrinsic\_procedure\_name}( \mathbf{x}, \text{expr\_list} ) \\
\mathbf{x} &= \text{intrinsic\_procedure\_name}( \text{expr\_list}, \mathbf{x} )
\end{align*}
\]

In the preceding statements:

- \(\mathbf{x}\) and \(\mathbf{v}\) (as applicable) are both scalar variables of intrinsic type.
- \(\mathbf{x}\) must not be an allocatable variable.
- During the execution of an atomic region, multiple syntactic occurrences of \(\mathbf{x}\) must designate the same storage location.
- None of \(\mathbf{v}\), \text{expr}, and \text{expr\_list} (as applicable) may access the same storage location as \(\mathbf{x}\).
- None of \(\mathbf{x}\), \text{expr}, and \text{expr\_list} (as applicable) may access the same storage location as \(\mathbf{v}\).
- \text{expr} is a scalar expression.
- \text{expr\_list} is a comma-separated, non-empty list of scalar expressions. If \text{intrinsic\_procedure\_name} refers to \text{iand}, \text{ior}, or \text{ieor}, exactly one expression must appear in \text{expr\_list}.
- \text{intrinsic\_procedure\_name} is one of \text{max}, \text{min}, \text{iand}, \text{ior}, or \text{ieor}. \text{operator} is one of \(+\), \(-\), \(/\), \%.\text{and.}, \%.\text{or.}, \%.\text{eqv.}, or \%.\text{neqv.}.
- The expression \(\mathbf{x} \text{ operator } \text{expr}\) must be mathematically equivalent to \(\mathbf{x} \text{ operator } (\text{expr})\). This requirement is satisfied if the operators in \text{expr} have precedence greater than \text{operator}, or by using parentheses around \text{expr} or subexpressions of \text{expr}.
- The expression \(\text{expr} \text{ operator } \mathbf{x}\) must be mathematically equivalent to \((\text{expr}) \text{ operator } \mathbf{x}\). This requirement is satisfied if the operators in \text{expr} have precedence equal to or greater than \text{operator}, or by using parentheses around \text{expr} or subexpressions of \text{expr}.
- \text{intrinsic\_procedure\_name} must refer to the intrinsic procedure name and not to other program entities.
- \text{operator} must refer to the intrinsic operator and not to a user-defined operator. All assignments must be intrinsic assignments.
- For forms that allow multiple occurrences of \(\mathbf{x}\), the number of times that \(\mathbf{x}\) is evaluated is unspecified.

An atomic construct with the read clause forces an atomic read of the location designated by \(\mathbf{x}\).

An atomic construct with the write clause forces an atomic write of the location designated by \(\mathbf{x}\).

An atomic construct with the update clause forces an atomic update of the location designated by \(\mathbf{x}\) using the designated operator or intrinsic. Note that when no clause is present, the semantics are equivalent to atomic update. Only the read and write of the location designated by \(\mathbf{x}\) are performed mutually atomically. The evaluation of \text{expr} or \text{expr\_list} need not be atomic with respect to the read or write of the location designated by \(\mathbf{x}\).
An **atomic** construct with the **capture** clause forces an atomic update of the location designated by $x$ using the designated operator or intrinsic while also capturing the original or final value of the location designated by $x$ with respect to the atomic update. The original or final value of the location designated by $x$ is written into the location designated by $v$ depending on the form of the **atomic** construct structured block or statements following the usual language semantics. Only the read and write of the location designated by $x$ are performed mutually atomically. Neither the evaluation of $expr$ or $expr$-list, nor the write to the location designated by $v$, need to be atomic with respect to the read or write of the location designated by $x$.

For all forms of the **atomic** construct, any combination of two or more of these **atomic** constructs enforces mutually exclusive access to the locations designated by $x$. To avoid race conditions, all accesses of the locations designated by $x$ that could potentially occur in parallel must be protected with an **atomic** construct.

Atomic regions do not guarantee exclusive access with respect to any accesses outside of atomic regions to the same storage location $x$ even if those accesses occur during the execution of a reduction clause.

If the storage location designated by $x$ is not size-aligned (that is, if the byte alignment of $x$ is not a multiple of the size of $x$), then the behavior of the atomic region is implementation-defined.

**Restrictions**

- All atomic accesses to the storage locations designated by $x$ throughout the program are required to have the same type and type parameters.
- Storage locations designated by $x$ must be less than or equal in size to the largest available native atomic operator width.

### 2.13. Declare Directive

**Summary** A **declare** directive is used in the declaration section of a Fortran subroutine, function, or module, or following a variable declaration in C or C++. It can specify that a variable or array is to be allocated in the device memory for the duration of the implicit data region of a function, subroutine or program, and specify whether the data values are to be transferred from the host to the device memory upon entry to the implicit data region, and from the device to the host memory upon exit from the implicit data region. These directives create a visible device copy of the variable or array.

**Syntax** In C and C++, the syntax of the **declare** directive is:

```
#pragma acc declare clause-list new-line
```

In Fortran the syntax of the **declare** directive is:

```
!$acc declare clause-list
```

where **clause** is one of the following:
copy( var-list )
copyin( var-list )
copyout( var-list )
create( var-list )
present( var-list )
deviceptr( var-list )
device_resident( var-list )
link( var-list )

The associated region is the implicit region associated with the function, subroutine, or program in which the directive appears. If the directive appears in the declaration section of a Fortran module subprogram or in a C or C++ global scope, the associated region is the implicit region for the whole program. The copy, copyin, copyout, present, and deviceptr data clauses are described in Section [2.7 Data Clauses].

Restrictions

- A declare directive must appear in the same scope as any variable or array in any of the data clauses on the directive.
- A variable or array may appear at most once in all the clauses of declare directives for a function, subroutine, program, or module.
- Subarrays are not allowed in declare directives.
- In Fortran, assumed-size dummy arrays may not appear in a declare directive.
- In Fortran, pointer arrays may be specified, but pointer association is not preserved in the device memory.
- In a Fortran module declaration section, only create, copyin, device_resident, and link clauses are allowed.
- In C or C++ global scope, only create, copyin, deviceptr, device_resident and link clauses are allowed.
- C and C++ extern variables may only appear in create, copyin, deviceptr, device_resident and link clauses on a declare directive.
- In C and C++, only global and extern variables may appear in a link clause. In Fortran, only module variables and common block names (enclosed in slashes) may appear in a link clause.
- In C or C++, a longjmp call in the region must return to a setjmp call within the region.
- In C++, an exception thrown in the region must be handled within the region.
- See Section [2.17 Fortran Optional Arguments] for discussion of Fortran optional dummy arguments in data clauses, including device_resident clauses.

2.13.1. device_resident clause

Summary The device_resident clause specifies that the memory for the named variables should be allocated in the accelerator device memory and not in the host memory. The names
in the argument list may be variable or array names, or Fortran common block names enclosed between slashes; subarrays are not allowed. The host may not be able to access variables in a device_resident clause. The accelerator data lifetime of global variables or common blocks specified in a device_resident clause is the entire execution of the program.

In Fortran, if the variable has the Fortran allocatable attribute, the memory for the variable will be allocated in and deallocated from the current accelerator device memory when the host program executes an allocate or deallocate statement for that variable. If the variable has the Fortran pointer attribute, it may be allocated or deallocated by the host in the accelerator device memory, or may appear on the left hand side of a pointer assignment statement, if the right hand side variable itself appears in a device_resident clause.

In Fortran, the argument to a device_resident clause may be a common block name enclosed in slashes; in this case, all declarations of the common block must have a matching device_resident clause. In this case, the common block will be statically allocated in device memory, and not in host memory. The common block will be available to accelerator routines; see Section 2.15 Procedure Calls in Compute Regions.

In a Fortran module declaration section, a variable or array in a device_resident clause will be available to accelerator subprograms.

In C or C++ global scope, a variable or array in a device_resident clause will be available to accelerator routines. A C or C++ extern variable may appear in a device_resident clause only if the actual declaration and all extern declarations are also followed by device_resident clauses.

2.13.2. create clause

If the current device is a shared memory device, no action is taken.

If the current device is a non-shared memory device, the create clause behaves as follows, for each var in var-list:

• At entry to an implicit data region where the declare directive appears:
  – If var is present, a present increment action with the structured reference count is performed. If var is a pointer reference, an attach action is performed.
  – Otherwise, a create action with the structured reference count is performed. If var is a pointer reference, an attach action is performed.

• At exit from an implicit data region where the declare directive appears:
  – If var is not present on the current device, a runtime error is issued.
  – Otherwise, a present decrement action with the structured reference count is performed. If var is a pointer reference, a detach action is performed. If both structured and dynamic reference counts are zero, a delete action is performed.

If the declare directive appears in a global context, then the data in var-list is statically allocated in device memory and the structured reference count is set to one.

In Fortran, if a variable var in var-list has the Fortran allocatable or pointer attribute, then:

• An allocate statement for var will allocate memory from both host memory as well as the
current accelerator device memory, and the dynamic reference count will be set to one.

- A `deallocate` statement for `var` will deallocate memory from both host memory as well as the current accelerator device memory, and the dynamic reference count will be set to zero.

If the structured reference count is not zero, a runtime error is issued.

In Fortran, if a variable `var` in `var-list` has the Fortran `pointer` attribute, then it may appear on the left hand side of a pointer assignment statement, if the right hand side variable itself appears in a `create` clause.

### 2.13.3. link clause

The `link` clause is used for large global host static data that is referenced within an accelerator routine and that should have a dynamic data lifetime on the device. The `link` clause specifies that only a global link for the named variables should be statically created in accelerator memory. The host data structure remains statically allocated and globally available. The device data memory will be allocated only when the global variable appears on a data clause for a `data` construct, compute construct, or `enter data` directive. The arguments to the `link` clause must be global data. In C or C++, the `link` clause must appear at global scope, or the arguments must be `extern` variables.

In Fortran, the `link` clause must appear in a `module` declaration section, or the arguments must be `common block` names enclosed in slashes. A `common block` that is listed in a `link` clause must be declared with the same size in all program units where it appears. A `declare link` clause must be visible everywhere the global variables or common block variables are explicitly or implicitly used in a data clause, compute construct, or accelerator routine. The global variable or `common block` variables may be used in accelerator routines. The accelerator data lifetime of variables or common blocks specified in a `link` clause is the data region that allocates the variable or common block with a data clause, or from the execution of the `enter data` directive that allocates the data until an `exit data` directive deallocates it or until the end of the program.

### 2.14. Executable Directives

#### 2.14.1. Init Directive

**Summary** The `init` directive tells the runtime to initialize the runtime for that device type. This can be used to isolate any initialization cost from the computational cost, when collecting performance statistics. If no device type is specified all devices will be initialized. An `init` directive may be used in place of a call to the `acc_init` runtime API routine, as described in Section 3.2.7

**Syntax** In C and C++, the syntax of the `init` directive is:

```
#pragma acc init [clause-list] new-line
```

In Fortran the syntax of the `init` directive is:

```
!$acc init [clause-list]
```

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where clause is one of the following:

```c
    device_type ( device-type-list )
    device_num ( int-exp )
```

1740 **device_type clause**

The `device_type` clause specifies the type of device that is to be initialized in the runtime. If the `device_type` clause is present, then the `acc-device-type-var` for the current thread is set to the argument value. If no `device_num` clause is present then all devices of this type are initialized.

1744 **device_num clause**

The `device_num` clause specifies the device id to be initialized. If the `device_num` clause is present, then the `acc-device-num-var` for the current thread is set to the argument value. If no `device_type` clause is specified, then the specified device id will be initialized for all available device types.

**Restrictions**

- This directive may not be called within a `compute` region.
- If the device type specified is not available, the behavior is implementation-defined; in particular, the program may abort.
- If the directive is called more than once without an intervening `acc_shutdown` call or `shutdown` directive, with a different value for the device type argument, the behavior is implementation-defined.
- If some accelerator regions are compiled to only use one device type, using this directive with a different device type may produce undefined behavior.

### 2.14.2. Shutdown Directive

**Summary** The `shutdown` directive tells the runtime to shut down the connection to the given accelerator device, and free any runtime resources. A `shutdown` directive may be used in place of a call to the `acc_shutdown` runtime API routine, as described in Section 3.2.8.

**Syntax** In C and C++, the syntax of the `shutdown` directive is:

```c
    #pragma acc shutdown [clause-list] new-line
```

In Fortran the syntax of the `shutdown` directive is:

```fortran
    !$acc shutdown [clause-list]
```

where clause is one of the following:
device_type (device-type-list)
device_num (int-expr)

device_type clause

The device_type clause specifies the type of device that is to be disconnected from the runtime. If no device_num clause is present then all devices of this type are disconnected.

device_num clause

The device_num clause specifies the device id to be disconnected. If no clauses are present then all available devices will be disconnected.

Restrictions

• This directive may not be used during the execution of a compute region.


Summary The set directive provides a means to modify internal control variables using directives. Each form of the set directive is functionally equivalent to a matching runtime API routine.

Syntax In C and C++, the syntax of the set directive is:

#pragma acc set [clause-list] new-line

In Fortran the syntax of the set directive is:

!$acc set [clause-list]

where clause is one of the following

default_async (int-expr)
device_num (int-expr)
device_type (device-type-list)

default_async clause

The default_async clause specifies the asynchronous queue that should be used if no queue is specified and changes the value of acc-default-async-var for the current thread to the argument value. If the value is acc_async_default, the value of acc-default-async-var will revert to the initial value, which is implementation-defined. A set default_async directive is functionally equivalent to a call to the acc_set_default_async runtime API routine, as described in Section 3.2.16.
device_num clause

The device_num clause specifies the device number to set as the default device for accelerator regions and changes the value of acc-device-num-var for the current thread to the argument value. If the value of device_num argument is negative, the runtime will revert to the default behavior, which is implementation-defined. A set device_num directive is functionally equivalent to the acc_set_device_num runtime API routine, as described in Section 3.2.4.

device_type clause

The device_type clause specifies the device type to set as the default device type for accelerator regions and sets the value of acc-device-type-var for the current thread to the argument value. If the value of the device_type argument is zero or the clause is not present, the selected device number will be used for all attached accelerator types. A set device_type directive is functionally equivalent to a call to the acc_set_device_type runtime API routine, as described in Section 3.2.2.

Restrictions

• This directive may not be used within a compute region.
• Passing default_async the value of acc_async_noval has no effect.
• Passing default_async the value of acc_async_sync will cause all asynchronous directives in the default asynchronous queue to become synchronous.
• Passing default_async the value of acc_async_default will restore the default asynchronous queue to the initial value, which is implementation-defined.
• If the value of device_num is larger than the maximum supported value for the given type, the behavior is implementation-defined.
• At least one clause must be specified.
• Two instances of the same clause may not appear on the same directive.

2.14.4. Update Directive

Summary The update directive is used during the lifetime of accelerator data to update all or part of local variables or arrays with values from the corresponding data in device memory, or to update all or part of device variables or arrays with values from the corresponding data in local memory.

Syntax In C and C++, the syntax of the update directive is:

    #pragma acc update clause-list new-line

In Fortran the syntax of the update data directive is:
!$acc update clause-list

where clause is one of the following:

async [( int-expr )]
wait [( int-expr-list )]
device_type( device-type-list )
if( condition )
if_present
self( var-list )
host( var-list )
device( var-list )

The var-list argument to an update clause is a comma-separated collection of variable names, array names, or subarray specifications. Multiple subarrays of the same array may appear in a var-list of the same or different clauses on the same directive. The effect of an update clause is to copy data from the accelerator device memory to the local memory for update self, and from local memory to accelerator device memory for update device. The updates are done in the order in which they appear on the directive. No action is taken for a variable or array in the self or device clause if there is no device copy of that variable or array. At least one self, host, or device clause must appear on the directive.

self clause

The self clause specifies that the variables, arrays, or subarrays in var-list are to be copied from the current accelerator device memory to the local memory for a non-shared memory accelerator. If the current accelerator shares memory with the encountering thread, no action is taken. An update directive with the self clause is equivalent to a call to the acc_update_self routine, described in Section 3.2.25.

host clause

The host clause is a synonym for the self clause.

device clause

The device clause specifies that the variables, arrays, or subarrays in var-list are to be copied from the local memory to the current accelerator device memory, for a non-shared memory accelerator. If the current accelerator shares memory with the encountering thread, no action is taken. Directive with the device clause is equivalent to a call to the acc_update_device routine, described in Section 3.2.24.

if clause

The if clause is optional; when there is no if clause, the implementation will generate code to perform the updates unconditionally. When an if clause appears, the implementation will generate
code to conditionally perform the updates only when the condition evaluates to nonzero in C or C++, or .true. in Fortran.

**async clause**

The async clause is optional; see Section 2.16 [Asynchronous Behavior] for more information.

**wait clause**

The wait clause is optional; see Section 2.16 [Asynchronous Behavior] for more information.

**if_present clause**

When an if_present clause appears on the directive, no action is taken for a variable or array which appears in var-list that is not present on the current device. When no if_present clause appears, all variables and arrays in a device or self clause must be present on the current device, and an implementation may halt the program with an error message if some data is not present.

**Restrictions**

- The update directive is executable. It must not appear in place of the statement following an if, while, do, switch, or label in C or C++, or in place of the statement following a logical if in Fortran.
- If no if_present clause appears on the directive, each variable and array that appears in var-list must be present on the current device.
- A variable or array that appears in var-list must be present on the current device.
- Only the async and wait clauses may follow a device_type clause.
- At most one if clause may appear. In Fortran, the condition must evaluate to a scalar logical value; in C or C++, the condition must evaluate to a scalar integer value.
- Noncontiguous subarrays may be specified. It is implementation-specific whether noncontiguous regions are updated by using one transfer for each contiguous subregion, or whether the noncontiguous data is packed, transferred once, and unpacked, or whether one or more larger subarrays (no larger than the smallest contiguous region that contains the specified subarray) are updated.
- In C and C++, a member of a struct or class may be specified, including a subarray of a member. Members of a subarray of struct or class type may not be specified.
- In C and C++, if a subarray notation is used for a struct member, subarray notation may not be used for any parent of that struct member.
- In Fortran, members of variables of derived type may be specified, including a subarray of a member. Members of subarrays of derived type may not be specified.
- In Fortran, if array or subarray notation is used for a derived type member, array or subarray notation may not be used for a parent of that derived type member.
2.15. Procedure Calls in Compute Regions

This section describes how routines are compiled for an accelerator and how procedure calls are compiled in compute regions. See Section 2.17 Fortran Optional Arguments for discussion of Fortran optional arguments in procedure calls inside compute regions.

2.15.1. Routine Directive

**Summary** The *routine* directive is used to tell the compiler to compile a given procedure for an accelerator as well as for the host. In a file or routine with a procedure call, the *routine* directive tells the implementation the attributes of the procedure when called on the accelerator.

**Syntax** In C and C++, the syntax of the *routine* directive is:

```
#pragma acc routine clause-list new-line
#pragma acc routine ( name ) clause-list new-line
```

In C and C++, the *routine* directive without a name may appear immediately before a function definition or just before a function prototype and applies to that immediately following function or prototype. The *routine* directive with a name may appear anywhere that a function prototype is allowed and applies to the function in that scope with that name, but must appear before any definition or use of that function.

In Fortran the syntax of the *routine* directive is:

```
!$acc routine clause-list
!$acc routine ( name ) clause-list
```
In Fortran, the **routine** directive without a name may appear within the specification part of a subroutine or function definition, or within an interface body for a subroutine or function in an interface block, and applies to the containing subroutine or function. The **routine** directive with a name may appear in the specification part of a subroutine, function or module, and applies to the named subroutine or function.

A C or C++ function or Fortran subprogram compiled with the **routine** directive for an accelerator is called an *accelerator routine*.

The *clause* is one of the following:

```
gang
worker
vector
seq
bind( name )
bind( string )
device_type( device-type-list )
nohost
```

A *gang*, *worker*, *vector*, or *seq* clause specifies the *level of parallelism* in the routine.

**gang clause**

The **gang** clause specifies that the procedure contains, may contain, or may call another procedure that contains a loop with a **gang** clause. A call to this procedure must appear in code that is executed in *gang-redundant* mode, and all gangs must execute the call. For instance, a procedure with a **routine gang** directive may not be called from within a loop that has a **gang** clause.

Only one of the *gang*, *worker*, *vector* and *seq* clauses may be specified for each device type.

**worker clause**

The **worker** clause specifies that the procedure contains, may contain, or may call another procedure that contains a loop with a **worker** clause, but does not contain nor does it call another procedure that contains a loop with the **gang** clause. A loop in this procedure with an **auto** clause may be selected by the compiler to execute in **worker** or **vector** mode. A call to this procedure must appear in code that is executed in **worker-single** mode, though it may be in **gang-redundant** or **gang-partitioned** mode. For instance, a procedure with a **routine worker** directive may be called from within a loop that has the **gang** clause, but not from within a loop that has the **worker** clause. Only one of the **gang**, **worker**, **vector**, and **seq** clauses may be specified for each device type.

**vector clause**

The **vector** clause specifies that the procedure contains, may contain, or may call another procedure that contains a loop with the **vector** clause, but does not contain nor does it call another procedure that contains a loop with either a **gang** or **worker** clause. A loop in this procedure with
an `auto` clause may be selected by the compiler to execute in `vector` mode, but not `worker` mode. A call to this procedure must appear in code that is executed in `vector-single` mode, though it may be in `gang-redundant` or `gang-partitioned` mode, and in `worker-single` or `worker-partitioned` mode. For instance, a procedure with a `routine` directive may be called from within a loop that has the `gang` clause or the `worker` clause, but not from within a loop that has the `vector` clause. Only one of the `gang`, `worker`, `vector`, and `seq` clauses may be specified for each device type.

**seq clause**

The `seq` clause specifies that the procedure does not contain nor does it call another procedure that contains a loop with a `gang`, `worker`, or `vector` clause. A loop in this procedure with an `auto` clause will be executed in `seq` mode. A call to this procedure may appear in any mode. Only one of the `gang`, `worker`, `vector` and `seq` clauses may be specified for each device type.

**bind clause**

The `bind` clause specifies the name to use when calling the procedure on the device. If the name is specified as an identifier, it is called as if that name were specified in the language being compiled. If the name is specified as a string, the string is used for the procedure name unmodified. A `bind` clause on a procedure definition behaves as if it had appeared on a declaration by changing the name used to call the function on the device; however, the procedure is not compiled for the device with either the original name or the name in the `bind` clause.

If there is both a Fortran `bind` and an acc `bind` clause for a procedure definition then a call on the host will call the Fortran bound name and a call on the device will call the name in the `bind` clause.

**device_type clause**

The `device_type` clause is described in Section 2.4 Device-Specific Clauses.

**nohost clause**

The `nohost` tells the compiler not to compile a version of this procedure for the host. All calls to this procedure must appear within compute regions. If this procedure is called from other procedures, those other procedures must also have a matching `routine` directive with the `nohost` clause.

**Restrictions**

- Only the `gang`, `worker`, `vector`, `seq` and `bind` clauses may follow a `device_type` clause.
- At least one of the (`gang`, `worker`, `vector`, or `seq`) clauses must be specified. If the `device_type` clause appears on the `routine` directive, a default level of parallelism clause must appear before the `device_type` clause, or a level of parallelism clause must be specified following each `device_type` clause on the directive.
• In C and C++, function static variables are not supported in functions to which a `routine` directive applies.

• In Fortran, variables with the `save` attribute, either explicitly or implicitly, are not supported in subprograms to which a `routine` directive applies.

• A `bind` clause may not bind to a routine name that has a visible `bind` clause.

• If a function or subroutine has a `bind` clause on both the declaration and the definition then they both must bind to the same name.

2.15.2. Global Data Access

C or C++ global, file static, or `extern` variables or array, and Fortran `module` or `common block` variables or arrays, that are used in accelerator routines must appear in a declare directive in a `create`, `copyin`, `device_resident` or `link` clause. If the data appears in a `device_resident` clause, the `routine` directive for the procedure must include the `nohost` clause. If the data appears in a `link` clause, that data must have an active accelerator data lifetime by virtue of appearing in a data clause for a `data` construct, compute construct, or `enter data` directive.

2.16. Asynchronous Behavior

This section describes the `async` clause and the behavior of programs that use asynchronous data movement and compute constructs, and asynchronous API routines.

2.16.1. `async` clause

The `async` clause may appear on a `parallel`, `kernels`, or `serial` construct, or an `enter data`, `exit data`, `update`, or `wait` directive. In all cases, the `async` clause is optional. When there is no `async` clause on a compute or data construct, the local thread will wait until the compute construct or data operations for the current device are complete before executing any of the code that follows. When there is no `async` clause on a `wait` directive, the local thread will wait until all operations on the appropriate asynchronous activity queues for the current device are complete. When there is an `async` clause, the parallel, kernels, or serial region or data operations may be processed asynchronously while the local thread continues with the code following the construct or directive.

The `async` clause may have a single `async-argument`, where an `async-argument` is a nonnegative scalar integer expression (`int` for C or C++, `integer` for Fortran), or one of the special `async` values defined below. The behavior with a negative `async-argument`, except the special `async` values defined below, is implementation-defined. The value of the `async-argument` may be used in a `wait` directive, `wait` clause, or various runtime routines to test or wait for completion of the operation.

Two special `async` values are defined in the C and Fortran header files and the Fortran `openacc` module. These are negative values, so as not to conflict with a user-specified nonnegative `async-argument`. An `async` clause with the `async-argument` `acc_async_noval` will behave the same as if the `async` clause had no argument. An `async` clause with the `async-argument` `acc_async_sync` will behave the same as if no `async` clause appeared.
The async-value of any operation is the value of the async-argument, if present, or the value of acc-default-async-var if it is acc_async_noval or if the async clause had no value, or acc_async_sync if no async clause appeared. If the current device supports asynchronous operation with one or more device activity queues, the async-value is used to select the queue on the current device onto which to enqueue an operation. The properties of the current device and the implementation will determine how many actual activity queues are supported, and how the async-value is mapped onto the actual activity queues. Two asynchronous operations with the same current device and the same async-value will be enqueued onto the same activity queue, and therefore will be executed on the device in the order they are encountered by the local thread. Two asynchronous operations with different async-values may be enqueued onto different activity queues, and therefore may be executed on the device in either order relative to each other. If there are two or more host threads executing and sharing the same accelerator device, two asynchronous operations with the same async-value will be enqueued on the same activity queue. If the threads are not synchronized with respect to each other, the operations may be enqueued in either order and therefore may execute on the device in either order. Asynchronous operations enqueued to different devices may execute in any order, regardless of the async-value used for each.

2.16.2. wait clause

The wait clause may appear on a parallel, kernels, or serial construct, or an enter data, exit data, or update directive. In all cases, the wait clause is optional. When there is no wait clause, the associated compute or update operations may be enqueued or launched or executed immediately on the device. If there is an argument to the wait clause, it must be a list of one or more async-arguments. The compute, data or update operation may not be launched or executed until all operations enqueued up to this point by this thread on the associated asynchronous device activity queues have completed. One legal implementation is for the local thread to wait for all the associated asynchronous device activity queues. Another legal implementation is for the local thread to enqueue the compute or update operation in such a way that the operation will not start until the operations enqueued on the associated asynchronous device activity queues have completed.

2.16.3. Wait Directive

Summary The wait directive causes the local thread to wait for completion of asynchronous operations on the current device, such as an accelerator parallel, kernels, or serial region or an update directive, or causes one device activity queue to synchronize with one or more other activity queues on the current device.

Syntax In C and C++, the syntax of the wait directive is:

```c
#pragma acc wait [( int-expr-list )] [clause-list] new-line
```

In Fortran the syntax of the wait directive is:

```fortran
!$acc wait [( int-expr-list )] [clause-list]
```
where clause is:

\[
\text{async } [\{ \text{int-expr} \}]
\]

The wait argument, if present, must be one or more async-arguments.

If there is no wait argument and no async clause, the local thread will wait until all operations enqueued by this thread on any activity queue on the current device have completed.

If there are one or more int-expr expressions and no async clause, the local thread will wait until all operations enqueued by this thread on each of the associated device activity queues have completed.

If there are two or more threads executing and sharing the same accelerator device, a wait directive with no async clause will cause the local thread to wait until all of the appropriate asynchronous operations previously enqueued by that thread have completed. To guarantee that operations have been enqueued by other threads requires additional synchronization between those threads. There is no guarantee that all the similar asynchronous operations initiated by other threads will have completed.

If there is an async clause, no new operation may be launched or executed on the async activity queue on the current device until all operations enqueued up to this point by this thread on the asynchronous activity queues associated with the wait argument have completed. One legal implementation is for the local thread to wait for all the associated asynchronous device activity queues. Another legal implementation is for the thread to enqueue a synchronization operation in such a way that no new operation will start until the operations enqueued on the associated asynchronous device activity queues have completed.

A wait directive is functionally equivalent to a call to one of the acc_wait, acc_wait_async, acc_wait_all or acc_wait_all_async runtime API routines, as described in Sections 3.2.11, 3.2.12, 3.2.13 and 3.2.14.

2.17. Fortran Optional Arguments

This section refers to the Fortran intrinsic function PRESENT. A call to the Fortran intrinsic function PRESENT(arg) returns .true., if arg is an optional dummy argument and an actual argument for arg was present in the argument list of the call site. This should not be confused with the OpenACC present data clause.

The appearance of a Fortran optional argument arg as a var in any of the following clauses has no effect at runtime if PRESENT(arg) is .false.:

- in data clauses on compute and data constructs;
- in data clauses on enter data and exit data directives;
- in data and device_resident clauses on declare directives;
- in use_device clauses on host data directives;
- in self, host, and device clauses on update directives.

The appearance of a Fortran optional argument arg in the following situations may result in undefined behavior if PRESENT(arg) is .false. when the associated construct is executed:
Fortran Optional Arguments

- as a \textit{var} in \texttt{private}, \texttt{firstprivate}, and \texttt{reduction} clauses;
- as a \textit{var} in \texttt{cache} directives;
- as part of an expression in any clause or directive.

A call to the Fortran intrinsic function \texttt{PRESENT} behaves the same way in a compute construct or an accelerator routine as on the host. The function call \texttt{PRESENT(arg)} must return the same value in a compute construct as \texttt{PRESENT(arg)} would outside of the compute construct. If a Fortran optional argument \texttt{arg} appears as an actual argument in a procedure call in a compute construct or an accelerator routine, and the associated dummy argument \texttt{subarg} also has the \texttt{optional} attribute, then \texttt{PRESENT(subarg)} returns the same value as \texttt{PRESENT(subarg)} would when executed on the host.
3. Runtime Library

This chapter describes the OpenACC runtime library routines that are available for use by programmers. Use of these routines may limit portability to systems that do not support the OpenACC API. Conditional compilation using the \_OPENACC preprocessor variable may preserve portability.

This chapter has two sections:

- Runtime library definitions
- Runtime library routines

There are four categories of runtime routines:

- Device management routines, to get the number of devices, set the current device, and so on.
- Asynchronous queue management, to synchronize until all activities on an async queue are complete, for instance.
- Device test routine, to test whether this statement is executing on the device or not.
- Data and memory management, to manage memory allocation or copy data between memories.

3.1. Runtime Library Definitions

In C and C++, prototypes for the runtime library routines described in this chapter are provided in a header file named openacc.h. All the library routines are extern functions with “C” linkage. This file defines:

- The prototypes of all routines in the chapter.
- Any datatypes used in those prototypes, including an enumeration type to describe types of accelerators.
- The values of acc_async_noval, acc_async_sync, and acc_async_default.

In Fortran, interface declarations are provided in a Fortran module named openacc. The openacc module defines:

- The integer parameter openacc_version with a value yyyy-mm where yyyy and mm are the year and month designations of the version of the Accelerator programming model supported. This value matches the value of the preprocessor variable \_OPENACC.
- Interfaces for all routines in the chapter.
- Integer parameters to define integer kinds for arguments to and return values for those routines.
• Integer parameters to describe types of accelerators.
• Integer parameters to define the values of acc_async_noval, acc_async_sync, and acc_async_default.

Many of the routines accept or return a value corresponding to the type of accelerator device. In C and C++, the datatype used for device type values is acc_device_t; in Fortran, the corresponding datatype is integer(kind=acc_device_kind). The possible values for device type are implementation specific, and are defined in the C or C++ include file openacc.h and the Fortran module openacc. Four values are always supported: acc_device_none, acc_device_default, acc_device_host, and acc_device_not_host. For other values, look at the appropriate files included with the implementation, or read the documentation for the implementation. The value acc_device_default will never be returned by any function; its use as an argument will tell the runtime library to use the default device type for that implementation.

3.2. Runtime Library Routines

In this section, for the C and C++ prototypes, pointers are typed h_void* or d_void* to designate a host address or device address, when these calls are executed on the host, as if the following definitions were included:

```c
#define h_void void
#define d_void void
```

Except for acc_on_device, these routines are only available on the host.

3.2.1. acc_get_num_devices

**Summary** The acc_get_num_devices routine returns the number of accelerator devices of the given type attached to the host.

**Format**

C or C++:

```c
int acc_get_num_devices( acc_device_t );
```

Fortran:

```fortran
integer function acc_get_num_devices( devicetype )
integer(acc_device_kind) :: devicetype
```

**Description** The acc_get_num_devices routine returns the number of accelerator devices of the given type attached to the host. The argument tells what kind of device to count.
Restrictions

- This routine may not be called within a compute region.

### 3.2.2. acc_set_device_type

**Summary** The `acc_set_device_type` routine tells the runtime which type of device to use when executing a compute region and sets the value of `acc-device-type-var`. This is useful when the implementation allows the program to be compiled to use more than one type of accelerator.

**Format**

C or C++:

```c
void acc_set_device_type( acc_device_t );
```

Fortran:

```fortran
subroutine acc_set_device_type( devicetype )
    integer(acc_device_kind) :: devicetype
```

**Description** The `acc_set_device_type` routine tells the runtime which type of device to use among those available and sets the value of `acc-device-type-var` for the current thread. A call to `acc_set_device_type` is functionally equivalent to a `set device_type` directive with the matching device type argument, as described in Section 2.14.3.

**Restrictions**

- This routine may not be called within a compute region.
- If the device type specified is not available, the behavior is implementation-defined; in particular, the program may abort.
- If some accelerator regions are compiled to only use one device type, calling this routine with a different device type may produce undefined behavior.

### 3.2.3. acc_get_device_type

**Summary** The `acc_get_device_type` routine returns the value of `acc-device-type-var`, which is the device type of the current device. This is useful when the implementation allows the program to be compiled to use more than one type of accelerator.

**Format**

C or C++:

```c
acc_device_t acc_get_device_type( void );
```
Fortran:
```fortran
function acc_get_device_type()
  integer(acc_device_kind) :: acc_get_device_type
end function acc_get_device_type
```

**Description**   The *acc_get_device_type* routine returns the value of *acc-device-type-var* for the current thread to tell the program what type of device will be used to run the next compute region, if one has been selected. The device type may have been selected by the program with an *acc_set_device_type* call, with an environment variable, or by the default behavior of the program.

**Restrictions**
- This routine may not be called within a compute region.
- If the device type has not yet been selected, the value *acc_device_none* may be returned.

### 3.2.4. acc_set_device_num

**Summary**   The *acc_set_device_num* routine tells the runtime which device to use among those attached of the given type for compute or data regions in the current thread and sets the value of *acc-device-num-var*.

**Format**
C or C++:
```c
void acc_set_device_num( int, acc_device_t );
```

Fortran:
```fortran
subroutine acc_set_device_num( devicenum, devicetype )
  integer :: devicenum
  integer(acc_device_kind) :: devicetype
end subroutine acc_set_device_num
```

**Description**   The *acc_set_device_num* routine tells the runtime which device to use among those attached of the given type for compute or data regions in the current thread and sets the value of *acc-device-num-var*. If the value of *devicenum* is negative, the runtime will revert to its default behavior, which is implementation-defined. If the value of the second argument is zero, the selected device number will be used for all attached accelerator types. A call to *acc_set_device_num* is functionally equivalent to a *set device_num* directive with the matching device number argument, as described in Section 2.14.3.

**Restrictions**
- This routine may not be called within a compute or data region.
- If the value of *devicenum* is greater than or equal to the value returned by *acc_get_num_devices* for that device type, the behavior is implementation-defined.
- Calling *acc_set_device_num* implies a call to *acc_set_device_type* with that device type argument.
### 3.2.5. `acc_get_device_num`

**Summary**  The `acc_get_device_num` routine returns the value of `acc-device-num-var` for the current thread.

**Format**

C or C++:

```c
int acc_get_device_num( acc_device_t );
```

Fortran:

```fortran
integer function acc_get_device_num( devicetype )
integer(acc_device_kind) :: devicetype
```

**Description**  The `acc_get_device_num` routine returns the value of `acc-device-num-var` for the current thread.

**Restrictions**  
- This routine may not be called within a compute region.

### 3.2.6. `acc_get_property`

**Summary**  The `acc_get_property` and `acc_get_property_string` routines return the value of a `device-property` for the specified device.

**Format**

C or C++:

```c
size_t acc_get_property( int devicenum, acc_device_t devicetype, acc_device_property_t property );
const char* acc_get_property_string( int devicenum, acc_device_t devicetype, acc_device_property_t property );
```

Fortran:

```fortran
function acc_get_property( devicenum, devicetype, property )
subroutine acc_get_property_string( devicenum, devicetype, property, string )
integer, value :: devicenum
integer(acc_device_kind), value :: devicetype
integer(acc_device_property), value :: property
integer(acc_device_property) :: acc_get_property
character(*) :: string
```
Description  The `acc_get_property` and `acc_get_property_string` routines returns the value of the specified `property`. `devicenum` and `devicetype` specify the device being queried. If `devicetype` has the value `acc_device_current`, then `devicenum` is ignored and the value of the property for the current device is returned. `property` is an enumeration constant, defined in `openacc.h`, for C or C++, or an integer parameter, defined in the `openacc` module, for Fortran. Integer-valued properties are returned by `acc_get_property`, and string-valued properties are returned by `acc_get_property_string`. In Fortran, `acc_get_property_string` returns the result into the `character` variable passed as the last argument.

The supported values of `property` are given in the following table.

<table>
<thead>
<tr>
<th>property</th>
<th>return type</th>
<th>return value</th>
</tr>
</thead>
<tbody>
<tr>
<td>acc_property_memory</td>
<td>integer</td>
<td>size of device memory in bytes</td>
</tr>
<tr>
<td>acc_property_free_memory</td>
<td>integer</td>
<td>free device memory in bytes</td>
</tr>
<tr>
<td>acc_property_name</td>
<td>string</td>
<td>device name</td>
</tr>
<tr>
<td>acc_property_vendor</td>
<td>string</td>
<td>device vendor</td>
</tr>
<tr>
<td>acc_property_driver</td>
<td>string</td>
<td>device driver version</td>
</tr>
</tbody>
</table>

An implementation may support additional properties for some devices.

Restrictions

- These routines may not be called within an compute region.
- If the value of `property` is not one of the known values for that query routine, or that property has no value for the specified device, `acc_get_property` will return 0 and `acc_get_property_string` will return NULL (in C or C++) or an blank string (in Fortran).

3.2.7. acc_init

Summary  The `acc_init` routine tells the runtime to initialize the runtime for that device type. This can be used to isolate any initialization cost from the computational cost, when collecting performance statistics.

Format

C or C++:

```c
void acc_init( acc_device_t );
```

Fortran:

```fortran
subroutine acc_init( devicetype )
    integer(acc_device_kind) :: devicetype
```

Description  The `acc_init` routine also implicitly calls `acc_set_device_type`. A call to `acc_init` is functionally equivalent to a `init` directive with the matching device type argument, as described in Section 2.14.1.
Restrictions

- This routine may not be called within a compute region.
- If the device type specified is not available, the behavior is implementation-defined; in particular, the program may abort.
- If the routine is called more than once without an intervening acc_shutdown call, with a different value for the device type argument, the behavior is implementation-defined.
- If some accelerator regions are compiled to only use one device type, calling this routine with a different device type may produce undefined behavior.

3.2.8. acc_shutdown

Summary The acc_shutdown routine tells the runtime to shut down the connection to the given accelerator device, and free up any runtime resources. A call to acc_shutdown is functionally equivalent to a shutdown directive with the matching device type argument, as described in Section 2.14.2.

Format

C or C++:

```c
void acc_shutdown( acc_device_t );
```

Fortran:

```fortran
subroutine acc_shutdown( devicetype )
  integer(acc_device_kind) :: devicetype
```

Description The acc_shutdown routine disconnects the program from the any accelerator device of the specified device type. Any data that is present on any such device is immediately deallocated.

Restrictions

- This routine may not be called during execution of a compute region.
- If the program attempts to execute a compute region or access any device data on such a device, the behavior is undefined.

3.2.9. acc_async_test

Summary The acc_async_test routine tests for completion of all associated asynchronous operations on the current device.

Format
C or C++:
```c
int acc_async_test( int );
```

Fortran:
```fortran
logical function acc_async_test( arg )
integer(acc_handle_kind) :: arg
```

**Description**  
The argument must be an *async-argument* as defined in Section 2.16.1 *async clause*. If that value did not appear in any *async* clauses, or if it did appear in one or more *async* clauses and all such asynchronous operations have completed on the current device, the `acc_async_test` routine will return with a nonzero value in C and C++, or `.true.` in Fortran. If some such asynchronous operations have not completed, the `acc_async_test` routine will return with a zero value in C and C++, or `.false.` in Fortran. If two or more threads share the same accelerator, the `acc_async_test` routine will return with a nonzero value or `.true.` only if all matching asynchronous operations initiated by this thread have completed; there is no guarantee that all matching asynchronous operations initiated by other threads have completed.

### 3.2.10. `acc_async_test_all`

**Summary**  
The `acc_async_test_all` routine tests for completion of all asynchronous operations.

**Format**

C or C++:
```c
int acc_async_test_all( );
```

Fortran:
```fortran
logical function acc_async_test_all( )
```

**Description**  
If all outstanding asynchronous operations have completed, the `acc_async_test_all` routine will return with a nonzero value in C and C++, or `.true.` in Fortran. If some asynchronous operations have not completed, the `acc_async_test_all` routine will return with a zero value in C and C++, or `.false.` in Fortran. If two or more threads share the same accelerator, the `acc_async_test_all` routine will return with a nonzero value or `.true.` only if all outstanding asynchronous operations initiated by this thread have completed; there is no guarantee that all asynchronous operations initiated by other threads have completed.

### 3.2.11. `acc_wait`

**Summary**  
The `acc_wait` routine waits for completion of all associated asynchronous operations on the current device.
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Format

C or C++:

```c
void acc_wait( int );
```

Fortran:

```fortran
subroutine acc_wait( arg )
integer(acc_handle_kind) :: arg
```

Description The argument must be an async-argument as defined in Section 2.16.1 async clause. If that value appeared in one or more async clauses, the acc_wait routine will not return until the latest such asynchronous operation has completed on the current device. If two or more threads share the same accelerator, the acc_wait routine will return only if all matching asynchronous operations initiated by this thread have completed; there is no guarantee that all matching asynchronous operations initiated by other threads have completed. For compatibility with version 1.0, this routine may also be spelled acc_async_wait. A call to acc_wait is functionally equivalent to a wait directive with a matching wait argument and no async clause, as described in Section 2.16.3.

3.2.12. acc_wait_async

Summary The acc_wait_async routine enqueues a wait operation on one async queue of the current device for the operations previously enqueued on another async queue.

Format

C or C++:

```c
void acc_wait_async( int, int );
```

Fortran:

```fortran
subroutine acc_wait_async( arg, async )
integer(acc_handle_kind) :: arg, async
```

Description The arguments must be async-arguments, as defined in Section 2.16.1 async clause. The routine will enqueue a wait operation on the appropriate device queue associated with the second argument, which will wait for operations enqueued on the device queue associated with the first argument. See Section 2.16.1 Asynchronous Behavior for more information. A call to acc_wait_async is functionally equivalent to a wait directive with a matching wait argument and a matching async argument, as described in Section 2.16.3.

3.2.13. acc_wait_all

Summary The acc_wait_all routine waits for completion of all asynchronous operations.

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Format

C or C++:

```c
void acc_wait_all( );
```

Fortran:

```fortran
subroutine acc_wait_all( )
```

Description The `acc_wait_all` routine will not return until the all asynchronous operations have completed. If two or more threads share the same accelerator, the `acc_wait_all` routine will return only if all asynchronous operations initiated by this thread have completed; there is no guarantee that all asynchronous operations initiated by other threads have completed. For compatibility with version 1.0, this routine may also be spelled `acc_async_wait_all`. A call to `acc_wait_all` is functionally equivalent to a `wait` directive with no wait argument list and no `async` argument, as described in Section 2.16.3.

3.2.14. acc_wait_all_async

Summary The `acc_wait_all_async` routine enqueues wait operations on one async queue for the operations previously enqueued on all other async queues.

Format

C or C++:

```c
void acc_wait_all_async( int );
```

Fortran:

```fortran
subroutine acc_wait_all_async( async )
  integer(acc_handle_kind) :: async
```

Description The argument must be an `async-argument` as defined in Section 2.16.1 `async clause`. The routine will enqueue a wait operation on the appropriate device queue for each other device queue. See Section 2.16 Asynchronous Behavior for more information. A call to `acc_wait_all_async` is functionally equivalent to a `wait` directive with no wait argument list and a matching `async` argument, as described in Section 2.16.3.

3.2.15. acc_get_default_async

Summary The `acc_get_default_async` routine returns the value of `acc-default-async-var` for the current thread.

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C or C++:

```c
int acc_get_default_async( void );
```

Fortran:

```fortran
function acc_get_default_async( )
  integer(acc_handle_kind) :: acc_get_default_async
end function acc_get_default_async
```

**Description**  The `acc_get_default_async` routine returns the value of `acc-default-async-var` for the current thread, which is the asynchronous queue used when an `async` clause appears without an `async-argument` or with the value `acc_async_noval`.

### 3.2.16. acc_set_default_async

**Summary**  The `acc_set_default_async` routine tells the runtime which asynchronous queue to use when no other queue is specified.

**Format**

C or C++:

```c
void acc_set_default_async( int async );
```

Fortran:

```fortran
subroutine acc_set_default_async( async )
  integer(acc_handle_kind) :: async
end subroutine acc_set_default_async
```

**Description**  The `acc_set_default_async` routine tells the runtime to place any directives with an `async` clause that does not have an `async-argument` or with the special `acc_async_noval` value into the specified asynchronous activity queue instead of the default asynchronous activity queue for that device by setting the value of `acc-default-async-var` for the current thread. The special argument `acc_async_default` will reset the default asynchronous activity queue to the initial value, which is implementation-defined. A call to `acc_set_default_async` is functionally equivalent to a `set default_async` directive with a matching argument in `int-expr`, as described in Section 2.14.3.

### 3.2.17. acc_on_device

**Summary**  The `acc_on_device` routine tells the program whether it is executing on a particular device.

**Format**
C or C++:

```c
int acc_on_device( acc_device_t);
```

Fortran:

```fortran
logical function acc_on_device( devicetype )
  integer(acc_device_kind) :: devicetype
```

### Description
The **acc_on_device** routine may be used to execute different paths depending on whether the code is running on the host or on some accelerator. If the **acc_on_device** routine has a compile-time constant argument, it evaluates at compile time to a constant. The argument must be one of the defined accelerator types. If the argument is **acc_device_host**, then outside of an accelerator compute region or accelerator routine, or in an accelerator compute region or accelerator routine that is executed on the host processor, this routine will evaluate to nonzero for C or C++, and `.true.` for Fortran; otherwise, it will evaluate to zero for C or C++, and `.false.` for Fortran. If the argument is **acc_device_not_host**, the result is the negation of the result with argument **acc_device_host**. If the argument is any accelerator device type, then in a compute region or routine that is executed on an accelerator of that device type, this routine will evaluate to nonzero for C or C++, and `.true.` for Fortran; otherwise, it will evaluate to zero for C or C++, and `.false.` for Fortran. The result with argument **acc_device_default** is undefined.

### 3.2.18. acc_malloc

#### Summary
The **acc_malloc** routine allocates memory on the accelerator device.

#### Format

C or C++:

```c
d_void* acc_malloc( size_t );
```

### Description
The **acc_malloc** routine may be used to allocate memory on the accelerator device. Pointers assigned from this function may be used in **deviceptr** clauses to tell the compiler that the pointer target is resident on the device.

### 3.2.19. acc_free

#### Summary
The **acc_free** routine frees memory on the accelerator device.

#### Format

C or C++:

```c
void acc_free( d_void* );
```

### Description
The **acc_free** routine will free previously allocated memory on the accelerator device; the argument should be a pointer value that was returned by a call to **acc_malloc**.
3.2.20. acc_copyin

Summary The acc_copyin routines test to see if the data is already present on the current device; if not, they allocate memory on the accelerator device to correspond to the specified host memory, and copy the data to that device memory, on a non-shared memory device.

Format

C or C++:
```c
  d_void* acc_copyin( h_void*, size_t );
  void acc_copyin_async( h_void*, size_t, int );
```

Fortran:
```fortran
  subroutine acc_copyin( a )
  subroutine acc_copyin( a, len )
  subroutine acc_copyin_async( a, async )
  subroutine acc_copyin_async( a, len, async )
    type(*), dimension(..) :: a
    integer :: len
    integer(acc_handle_kind) :: async
```

Description The acc_copyin routines are equivalent to the enter data directive with a copyin clause, as described in Section 2.7.6. In C, the arguments are a pointer to the data and length in bytes; the synchronous function returns a pointer to the allocated device space, as with acc_malloc. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes.

The behavior of the acc_copyin routines is:

- If the current device is a shared memory device, no action is taken. The C acc_copyin returns the incoming pointer.
- If the data is present, a present increment action with the dynamic reference count is performed. The C acc_copyin returns a pointer to the existing device memory.
- Otherwise, a copyin action with the appropriate reference count is performed. The C acc_copyin returns the device address of the newly allocated memory.

This data may be accessed using the present data clause. Pointers assigned from the C acc_copyin function may be used in deviceptr clauses to tell the compiler that the pointer target is resident on the device.

The _async versions of this function will perform any data transfers asynchronously on the async queue associated with the value passed in as the async argument. The function may return before the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The synchronous versions will not return until the data has been completely transferred.

For compatibility with OpenACC 2.0, acc_present_or_copyin and acc_pcopyin are alternate names for acc_copyin.
3.2.21. acc_create

Summary  The acc_create routines test to see if the data is already present on the device; if not, they allocate memory on the accelerator device to correspond to the specified host memory, on a non-shared memory device.

Format

C or C++:

d_void* acc_create( h_void*, size_t );
void acc_create_async( h_void*, size_t, int async );

Fortran:

subroutine acc_create( a )
subroutine acc_create( a, len )
subroutine acc_create_async( a, async )
subroutine acc_create_async( a, len, async )
type(*), dimension(..) :: a
integer :: len
integer(acc_handle_kind) :: async

Description  The acc_create routines are equivalent to the enter data directive with a create clause, as described in Section 2.7.8. In C, the arguments are a pointer to the data and length in bytes; the synchronous function returns a pointer to the allocated device space, as with acc_malloc. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes.

The behavior of the acc_create routines is:

• If the current device is a shared memory device, no action is taken. The C acc_create returns the incoming pointer.

• If the data is present, a present increment action with the dynamic reference count is performed. The C acc_create returns a pointer to the existing device memory.

• Otherwise, a create action with the appropriate reference count is performed. The C acc_create returns the device address of the newly allocated memory.

This data may be accessed using the present data clause. Pointers assigned from the C acc_copyin function may be used in deviceptr clauses to tell the compiler that the pointer target is resident on the device.

The _async versions of these function may perform the data allocation asynchronously on the async queue associated with the value passed in as the async argument. The synchronous versions will not return until the data has been allocated.

For compatibility with OpenACC 2.0, acc_present_or_create and acc_pcreate are alternate names for acc_create.
3.2.22. acc_copyout

Summary  The acc_copyout routines copy data from device memory to the corresponding local memory, then deallocate that memory from the accelerator device, on a non-shared memory device.

Format

C or C++:

```c
void acc_copyout( h_void*, size_t );
void acc_copyout_async( h_void*, size_t, int async );
void acc_copyout_finalize( h_void*, size_t );
void acc_copyout_finalize_async( h_void*, size_t, int async );
```

Fortran:

```fortran
subroutine acc_copyout( a )
subroutine acc_copyout( a, len )
subroutine acc_copyout_async( a, async )
subroutine acc_copyout_async( a, len, async )
subroutine acc_copyout_finalize( a )
subroutine acc_copyout_finalize( a, len )
subroutine acc_copyout_finalize_async( a, async )
subroutine acc_copyout_finalize_async( a, len, async )

type(*), dimension(..) :: a
integer :: len
integer(acc_handle_kind) :: async
```

Description  The acc_copyout routines are equivalent to the exit data directive with a copyout clause, and the acc_copyout_finalize routines are equivalent to the exit data directive with both copyout and finalize clauses, as described in Section 2.7.7. In C, the arguments are a pointer to the data and length in bytes. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes.

The behavior of the acc_copyout routines is:

- If the current device is a shared memory device, no action is taken.
- If the data is not present, a runtime error is issued.
- Otherwise, a present decrement action with the dynamic reference count is performed (acc_copyout), or the dynamic reference count is set to zero (acc_copyout_finalize). If both reference counts are then zero, a copyout action is performed.

The _async versions of these functions will perform any associated data transfers asynchronously on the async queue associated with the value passed in as the async argument. The function may return before the data has been transferred or deallocated; see Section 2.16 Asynchronous Behavior for more details. The synchronous versions will not return until the data has been completely transferred. Even if the data has not been transferred or deallocated before the function returns, the data will be treated as not present on the device.
3.2.23. acc_delete

Summary  The acc_delete routines deallocate the memory from the accelerator device corresponding to the specified local memory, on a non-shared memory device.

Format

C or C++:

```c
void acc_delete( h_void*, size_t );
void acc_delete_async( h_void*, size_t, int async );
void acc_delete_finalize( h_void*, size_t );
void acc_delete_finalize_async( h_void*, size_t, int async );
```

Fortran:

```fortran
subroutine acc_delete( a )
subroutine acc_delete( a, len )
subroutine acc_delete_async( a, async )
subroutine acc_delete_async( a, len, async )
subroutine acc_delete_finalize( a )
subroutine acc_delete_finalize( a, len )
subroutine acc_delete_finalize_async( a, async )
subroutine acc_delete_finalize_async( a, len, async )
type(*), dimension(..) :: a
integer :: len
integer(acc_handle_kind) :: async
```

Description  The acc_delete routines are equivalent to the exit data directive with a delete clause, and the acc_delete_finalize routines are equivalent to the exit data directive with both delete clause and finalize clauses, as described in Section 2.7.10 The arguments are as for acc_copyout.

The behavior of the acc_delete routines is:

- If the current device is a shared memory device, no action is taken.
- If the data is not present, a runtime error is issued.
- Otherwise, a present decrement action with the dynamic reference count is performed (acc_delete), or the dynamic reference count is set to zero (acc_delete_finalize). If both reference counts are then zero, a delete action is performed.

The _async versions of these function may perform the data deallocation asynchronously on the async queue associated with the value passed in as the async argument. The synchronous versions will not return until the data has been deallocated. Even if the data has not been deallocated before the function returns, the data will be treated as not present on the device.
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3.2.24. acc_update_device

Summary  The acc_update_device routine updates the device copy of data from the corresponding local memory on a non-shared memory device.

Format

C or C++:

```c
void acc_update_device( h_void*, size_t );
void acc_update_device_async( h_void*, size_t, int async );
```

Fortran:

```fortran
subroutine acc_update_device( a )
subroutine acc_update_device( a, len )
subroutine acc_update_device( a, async )
subroutine acc_update_device( a, len, async )
    type(*), dimension(..) :: a
    integer :: len
    integer(acc_handle_kind) :: async
```

Description  The acc_update_device routine is equivalent to the update directive with a device clause, as described in Section 2.14.4. In C, the arguments are a pointer to the data and length in bytes. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes. On a non-shared memory device, the data in the local memory is copied to the corresponding device memory. It is a runtime error to call this routine if the data is not present on the device.

The _async versions of this function will perform the data transfers asynchronously on the async queue associated with the value passed in as the async argument. The function may return before the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The synchronous versions will not return until the data has been completely transferred.

3.2.25. acc_update_self

Summary  The acc_update_self routine updates the device copy of data to the corresponding local memory on a non-shared memory device.

Format

C or C++:

```c
void acc_update_self( h_void*, size_t );
void acc_update_self_async( h_void*, size_t, int async );
```

Fortran:
subroutine acc_update_self( a )
subroutine acc_update_self( a, len )
subroutine acc_update_self_async( a, async )
subroutine acc_update_self_async( a, len, async )

Description  The acc_update_self routine is equivalent to the update directive with a self clause, as described in Section 2.14.4. In C, the arguments are a pointer to the data and length in bytes. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes. On a non-shared memory device, the data in the local memory is copied to the corresponding device memory. There must be a device copy of the data on the device when calling this routine, otherwise no action is taken by the routine.

The _async versions of this function will perform the data transfers asynchronously on the async queue associated with the value passed in as the async argument. The function may return before the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The synchronous versions will not return until the data has been completely transferred.

3.2.26. acc_map_data

Summary  The acc_map_data routine maps previously allocated device data to the specified host data.

Format  
C or C++:

void acc_map_data( h_void*, d_void*, size_t );

Description  The acc_map_data routine is similar to an enter data directive with a create clause, except instead of allocating new device memory to start a data lifetime, the device address to use for the data lifetime is specified as an argument. The first argument is a host address, followed by the corresponding device address and the data length in bytes. After this call, when the host data appears in a data clause, the specified device memory will be used. It is an error to call acc_map_data for host data that is already present on the device. It is undefined to call acc_map_data with a device address that is already mapped to host data. The device address may be the result of a call to acc_malloc, or may come from some other device-specific API routine.

3.2.27. acc_unmap_data

Summary  The acc_unmap_data routine unmaps device data from the specified host data.
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Format

C or C++:

```c
void acc_unmap_data( h_void* );
```

Description The `acc_unmap_data` routine is similar to an `exit data` directive with a `delete` clause, except the device memory is not deallocated. The argument is pointer to the host data. A call to this routine ends the data lifetime for the specified host data. The device memory is not deallocated. It is undefined behavior to call `acc_unmap_data` with a host address unless that host address was mapped to device memory using `acc_map_data`.

3.2.28. acc_deviceptr

Summary The `acc_deviceptr` routine returns the device pointer associated with a specific host address.

Format

C or C++:

```c
d_void* acc_deviceptr( h_void* );
```

Description The `acc_deviceptr` routine returns the device pointer associated with a host address. The argument is the address of a host variable or array that has an active lifetime on the current device. If the data is not present on the device, the routine returns a NULL value.

3.2.29. acc_hostptr

Summary The `acc_hostptr` routine returns the host pointer associated with a specific device address.

Format

C or C++:

```c
h_void* acc_hostptr( d_void* );
```

Description The `acc_hostptr` routine returns the host pointer associated with a device address. The argument is the address of a device variable or array, such as that returned from `acc_deviceptr`, `acc_create` or `acc_copyin`. If the device address is NULL, or does not correspond to any host address, the routine returns a NULL value.

3.2.30. acc_is_present

Summary The `acc_is_present` routine tests whether a host variable or array region is present on the device.

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Format

C or C++:

```c
int acc_is_present( h_void*, size_t );
```

Fortran:

```fortran
logical function acc_is_present( a )
logical function acc_is_present( a, len )
type(*), dimension(..) :: a
integer :: len
```

Description  The `acc_is_present` routine tests whether the specified host data is present on the device. In C, the arguments are a pointer to the data and length in bytes; the function returns nonzero if the specified data is fully present, and zero otherwise. In Fortran, two forms are supported. In the first, the argument is a contiguous array section of intrinsic type. In the second, the first argument is a variable or array element and the second is the length in bytes. The function returns `.true.` if the specified data is fully present, and `.false.` otherwise. If the byte length is zero, the function returns nonzero in C or `.true.` in Fortran if the given address is present at all on the device.

3.2.31. acc_memcpy_to_device

Summary  The `acc_memcpy_to_device` routine copies data from local memory to device memory.

Format

C or C++:

```c
void acc_memcpy_to_device( d_void* dest, h_void* src, size_t bytes );
void acc_memcpy_to_device_async( d_void* dest, h_void* src, size_t bytes, int async );
```

Description  The `acc_memcpy_to_device` routine copies `bytes` of data from the local address in `src` to the device address in `dest`. The destination address must be a device address, such as would be returned from `acc_malloc` or `acc_deviceptr`.

The `_async` version of this function will perform the data transfers asynchronously on the async queue associated with the value passed in as the `async` argument. The function may return before the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The synchronous versions will not return until the data has been completely transferred.

3.2.32. acc_memcpy_from_device

Summary  The `acc_memcpy_from_device` routine copies data from device memory to local memory.
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Format

C or C++:

void acc_memcpy_from_device( h_void* dest, d_void* src, size_t bytes );
void acc_memcpy_from_device_async( h_void* dest, d_void* src,
size_t bytes, int async );

Description  The acc_memcpy_from_device routine copies bytes data from the device
address in src to the local address in dest. The source address must be a device address, such as
would be returned from acc_malloc or acc_deviceptr.

The _async version of this function will perform the data transfers asynchronously on the async
queue associated with the value passed in as the async argument. The function may return be-
fore the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The
synchronous versions will not return until the data has been completely transferred.

3.2.33. acc_memcpy_device

Summary  The acc_memcpy_device routine copies data from one memory location to an-
other memory location on the current device.

Format

C or C++:

void acc_memcpy_device( d_void* dest, d_void* src, size_t bytes );
void acc_memcpy_device_async( d_void* dest, d_void* src,
size_t bytes, int async );

Description  The acc_memcpy_device routine copies bytes data from the device address
in src to the device address in dest. Both addresses must be addresses in the current device
memory, such as would be returned from acc_malloc or acc_deviceptr. If dest and src
overlap, the behavior is undefined.

The _async version of this function will perform the data transfers asynchronously on the async
queue associated with the value passed in as the async argument. The function may return be-
fore the data has been transferred; see Section 2.16 Asynchronous Behavior for more details. The
synchronous versions will not return until the data has been completely transferred.

3.2.34. acc_attach

Summary  The acc_attach routine updates a pointer in device memory to point to the corre-
sponding device copy of the host pointer target.

Format
C or C++:

```c
void acc_attach( h_void** ptr );
void acc_attach_async( h_void** ptr, int async );
```

**Description** The `acc_attach` routines are passed the address of a host pointer. If the current device is a shared memory device, or if the pointer `*ptr` is not present on the current device, or the address to which the `*ptr` points is not present on the current device, no action is taken. Otherwise, these routines perform the `attach` action (Section 2.7.2).

These routines may issue a data transfer from local memory to device memory. The `_async` version of this function will perform the data transfers asynchronously on the async queue associated with the value passed in as the `async` argument. The function may return before the data has been transferred; see Section 2.16 [Asynchronous Behavior] for more details. The synchronous version will not return until the data has been completely transferred.

### 3.2.35. acc_detach

**Summary** The `acc_detach` routine updates a pointer in device memory to point to the host pointer target.

**Format**

C or C++:

```c
void acc_detach( h_void** ptr );
void acc_detach_async( h_void** ptr, int async );
void acc_detach_finalize( h_void** ptr );
void acc_detach_finalize_async( h_void** ptr, int async );
```

**Description** The `acc_detach` routines are passed the address of a host pointer. If the current device is a shared memory device, or if the pointer `*ptr` is not present on the current device, or if the attachment counter for the pointer `*ptr` is zero, no action is taken. Otherwise, these routines perform the `detach` action (Section 2.7.2).

The `acc_detach_finalize` routines are equivalent to an `exit data` directive with `detach` and `finalize` clauses, as described in Section 2.7.12 [detach clause]. If the current device is a shared memory device, or if the pointer `*ptr` is not present on the current device, or if the attachment counter for the pointer `*ptr` is zero, no action is taken. Otherwise, these routines perform the `immediate detach` action (Section 2.7.2).

These routines may issue a data transfer from local memory to device memory. The `_async` versions of these functions will perform the data transfers asynchronously on the async queue associated with the value passed in as the `async` argument. These functions may return before the data has been transferred; see Section 2.16 [Asynchronous Behavior] for more details. The synchronous versions will not return until the data has been completely transferred.
4. Environment Variables

This chapter describes the environment variables that modify the behavior of accelerator regions. The names of the environment variables must be upper case. The values assigned environment variables are case-insensitive and may have leading and trailing white space. If the values of the environment variables change after the program has started, even if the program itself modifies the values, the behavior is implementation-defined.

4.1. ACC_DEVICE_TYPE

The ACC_DEVICE_TYPE environment variable controls the default device type to use when executing accelerator parallel, kernels, and serial regions, if the program has been compiled to use more than one different type of device. The allowed values of this environment variable are implementation-defined. See the release notes for currently-supported values of this environment variable.

Example:
```
setenv ACC_DEVICE_TYPE NVIDIA
export ACC_DEVICE_TYPE=NVIDIA
```

4.2. ACC_DEVICE_NUM

The ACC_DEVICE_NUM environment variable controls the default device number to use when executing accelerator regions. The value of this environment variable must be a nonnegative integer between zero and the number of devices of the desired type attached to the host. If the value is greater than or equal to the number of devices attached, the behavior is implementation-defined.

Example:
```
setenv ACC_DEVICE_NUM 1
export ACC_DEVICE_NUM=1
```

4.3. ACC_PROFLIB

The ACC_PROFLIB environment variable specifies the profiling library. More details about the evaluation at runtime is given in section 5.3.3 Runtime Dynamic Library Loading.

Example:
```
setenv ACC_PROFLIB /path/to/proflib/libaccprof.so
export ACC_PROFLIB=/path/to/proflib/libaccprof.so
```
5. Profiling Interface

This chapter describes the OpenACC interface for tools that can be used for profile and trace data collection. Therefore it provides a set of OpenACC-specific event callbacks that are triggered during the application run. Currently, this interface does not support tools that employ asynchronous sampling. In this chapter, the term runtime refers to the OpenACC runtime library. The term library refers to the third party routines invoked at specified events by the OpenACC runtime.

There are four steps for interfacing a library to the runtime. The first is to write the data collection library callback routines. Section 5.1. Events describes the supported runtime events and the order in which callbacks to the callback routines will occur. Section 5.2. Callbacks Signature describes the signature of the callback routines for all events.

The second is to use registration routines to register the data collection callbacks for the appropriate events. The data collection and registration routines are then saved in a static or dynamic library or shared object. The third is to load the library at runtime. The library may be statically linked to the application or dynamically loaded by the application or by the runtime. This is described in Section 5.3. Loading the Library.

The fourth step is to invoke the registration routine to register the desired callbacks with the events. This may be done explicitly by the application, if the library is statically linked with the application, implicitly by including a call to the registration routine in a .init section, or by including an initialization routine in the library if it is dynamically loaded by the runtime. This is described in Section 5.4. Registering Event Callbacks.

Subsequently, the library may collect information when the callback routines are invoked by the runtime and process or store the acquired data.

5.1. Events

This section describes the events that are recognized by the runtime. Most events may have a start and end callback routine, that is, a routine that is called just before the runtime code to handle the event starts and another routine that is called just after the event is handled. The event names and routine prototypes are available in the header file acc_prof.h, which is delivered with the OpenACC implementation. Event names are prefixed with acc_ev_.

The ordering of events must reflect the order in which the OpenACC runtime actually executes them, i.e. if a runtime moves the enqueuing of data transfers or kernel launches outside the originating clauses/constructs, it needs to issue the corresponding launch callbacks when they really occur. A callback for a start event must always precede the matching end callback. The behavior of a tool receiving a callback after the runtime shutdown callback is undefined.

The events that the runtime supports can be registered with a callback and are defined in the enumeration type acc_event_t.
typedef enum acc_event_t{
    acc_ev_none = 0,
    acc_ev_device_init_start,
    acc_ev_device_init_end,
    acc_ev_device_shutdown_start,
    acc_ev_device_shutdown_end,
    acc_ev_runtime_shutdown,
    acc_ev_create,
    acc_ev_delete,
    acc_ev_alloc,
    acc_ev_free,
    acc_ev_enter_data_start,
    acc_ev_enter_data_end,
    acc_ev_exit_data_start,
    acc_ev_exit_data_end,
    acc_ev_update_start,
    acc_ev_update_end,
    acc_ev_compute_construct_start,
    acc_ev_compute_construct_end,
    acc_ev_enqueue_launch_start,
    acc_ev_enqueue_launch_end,
    acc_ev_enqueue_upload_start,
    acc_ev_enqueue_upload_end,
    acc_ev_enqueue_download_start,
    acc_ev_enqueue_download_end,
    acc_ev_wait_start,
    acc_ev_wait_end,
    acc_ev_last
} acc_event_t;

5.1.1. Runtime Initialization and Shutdown

No callbacks can be registered for the runtime initialization. Instead the initialization of the tool is handled as described in Section 5.3 Loading the Library.

The runtime shutdown event name is

acc_ev_runtime_shutdown

The acc_ev_runtime_shutdown event is triggered before the OpenACC runtime shuts down, either because all devices have been shutdown by calls to the acc_shutdown API routine, or at the end of the program.

5.1.2. Device Initialization and Shutdown

The device initialization event names are

acc_ev_device_init_start

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acc_ev_device_init_end

These events are triggered when a device is being initialized by the OpenACC runtime. This may be
when the program starts, or may be later during execution when the program reaches an acc_init
call or an OpenACC construct. The acc_ev_device_init_start is triggered before device
initialization starts and acc_ev_device_init_end after initialization is complete.

The device shutdown event names are

acc_ev_device_shutdown_start
acc_ev_device_shutdown_end

These events are triggered when a device is shut down, most likely by a call to the OpenACC
acc_shutdown API routine. The acc_ev_device_shutdown_start is triggered before
the device shutdown process starts and acc_ev_device_shutdown_end after the device shut-
down is complete.

5.1.3. Enter Data and Exit Data

The enter data and exit data event names are

acc_ev_enter_data_start
acc_ev_enter_data_end
acc_ev_exit_data_start
acc_ev_exit_data_end

The acc_ev_enter_data_start and acc_ev_enter_data_end events are triggered at
target directives, entry to data constructs, and entry to implicit data regions such as those
generated by compute constructs. The acc_ev_enter_data_start event is triggered before
any data allocation, data update, or wait events that are associated with that directive or region entry,
and the acc_ev_enter_data_end is triggered after those events.

The acc_ev_exit_data_start and acc_ev_exit_data_end events are triggered at exit
data directives, exit from data constructs, and exit from implicit data regions. The acc_ev_exit_data_start
event is triggered before any data deallocation, data update, or wait events associated with that di-
rective or region exit, and the acc_ev_exit_data_end event is triggered after those events.

When the construct that triggers an enter data or exit data event was generated implicitly by the
compiler the implicit field in the event structure will be set to 1. When the construct that
triggers these events was specified explicitly by the application code the implicit field in the
event structure will be set to 0.

5.1.4. Data Allocation

The data allocation event names are

acc_ev_create
acc_ev_delete
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```
acc_ev_alloc
acc_ev_free
```

An `acc_ev_alloc` event is triggered when the OpenACC runtime allocates memory from the device memory pool, and an `acc_ev_free` event is triggered when the runtime frees that memory.

An `acc_ev_create` event is triggered when the OpenACC runtime associates device memory with host memory, such as for a data clause (`create, copyin, copy, copyout`) at entry to a data construct, compute construct, at an `enter data` directive, or in a call to a data API routine (`acc_copyin, acc_create, ...`). An `acc_ev_create` event may be preceded by an `acc_ev_alloc` event, if newly allocated memory is used for this device data, or it may not, if the runtime manages its own memory pool.

An `acc_ev_delete` event is triggered when the OpenACC runtime disassociates device memory from host memory, such as for a data clause at exit from a data construct, compute construct, at an `exit data` directive, or in a call to a data API routine (`acc_copyout, acc_delete, ...`). An `acc_ev_delete` event may be followed by an `acc_ev_free` event, if the disassociated device memory is freed, or it may not, if the runtime manages its own memory pool.

When the action that generates a `data allocation` event was generated explicitly by the application code the `implicit` field in the event structure will be set to 0. When the `data allocation` event is triggered because of a variable or array with implicitly-determined data attributes or otherwise implicitly by the compiler the `implicit` field in the event structure will be set to 1.

5.1.5. Data Construct

The events for entering and leaving `data constructs` are mapped to `enter data` and `exit data` events as described in Section 5.1.3 Enter Data and Exit Data.

5.1.6. Update Directive

The `update directive` event names are

```
acc_ev_update_start
acc_ev_update_end
```

The `acc_ev_update_start` event will be triggered at an `update` directive, before any `data update` or `wait` events that are associated with the update directive are carried out, and the corresponding `acc_ev_update_end` event will be triggered after any of the associated events.

5.1.7. Compute Construct

The `compute construct` event names are

```
acc_ev_compute_construct_start
acc_ev_compute_construct_end
```

The `acc_ev_compute_construct_start` event is triggered at entry to a compute construct, before any `launch` events that are associated with entry to the compute construct. The `acc_ev_compute_construct_end`
event is triggered at the exit of the compute construct, after any launch events associated with exit from the compute construct. If there are data clauses on the compute construct, those data clauses may be treated as part of the compute construct, or as part of a data construct containing the compute construct. The callbacks for data clauses must use the same line numbers as for the compute construct events.

5.1.8. Enqueue Kernel Launch

The launch event names are

```
acc_ev_enqueue_launch_start
acc_ev_enqueue_launch_end
```

The acc_ev_enqueue_launch_start event is triggered just before an accelerator computation is enqueued for execution on the device, and acc_ev_enqueue_launch_end is triggered just after the computation is enqueued. Note that these events are synchronous with the host enqueuing the computation to the device, not with the device executing the computation.

The acc_ev_enqueue_launch_start event callback routine is invoked just before the computation is enqueued, not just before the computation starts execution. More importantly, the acc_ev_enqueue_launch_end event callback routine is invoked after the computation is enqueued, not after the computation finished executing.

Note: Measuring the time between the start and end launch callbacks is often unlikely to be useful, since it will only measure the time to manage the launch queue, not the time to execute the code on the device.

5.1.9. Enqueue Data Update (Upload and Download)

The data update event names are

```
acc_ev_enqueue_upload_start
acc_ev_enqueue_upload_end
acc_ev_enqueue_download_start
acc_ev_enqueue_download_end
```

The _start events are triggered just before each upload (data copy from host to device) operation is or download (data copy from device to host) operation is enqueued for execution on the device. The corresponding _end events are triggered just after each upload or download operation is enqueued.

Note: Measuring the time between the start and end update callbacks is often unlikely to be useful, since it will only measure the time to manage the enqueue operation, not the time to perform the actual upload or download.

When the action that generates a data update event was generated explicitly by the application code the implicit field in the event structure will be set to 0. When the data allocation event is triggered because of a variable or array with implicitly-determined data attributes or otherwise implicitly by the compiler the implicit field in the event structure will be set to 1.
5.1.10. Wait

The wait event names are

\[ \text{acc\_ev\_wait\_start} \]
\[ \text{acc\_ev\_wait\_end} \]

An \text{acc\_ev\_wait\_start} will be triggered for each relevant queue before the host thread waits for that queue to be empty. A \text{acc\_ev\_wait\_end} will be triggered for each relevant queue after the host thread has determined that the queue is empty.

Wait events occur when the host and device synchronize, either due to a \text{wait} directive or by a \text{wait} clause on a synchronous data construct, compute construct, or \text{enter data}, \text{exit data}, or \text{update} directive. For \text{wait} events triggered by an explicit synchronous \text{wait} directive or \text{wait} clause, the implicit field in the event structure will be 0. For all other wait events, the implicit field in the event structure will be 1.

The OpenACC runtime need not trigger \text{wait} events for queues that have not been used in the program, and need not trigger \text{wait} events for queues that have not been used by this thread since the last \text{wait} operation. For instance, an \text{acc\_wait} directive with no arguments is defined to wait on all queues. If the program only uses the default (synchronous) queue and the queue associated with \text{async(1)} and \text{async(2)} then an \text{acc\_wait} directive may trigger \text{wait} events only for those three queues. If the implementation knows that no activities have been enqueued on the \text{async(2)} queue since the last \text{wait} operation, then the \text{acc\_wait} directive may trigger \text{wait} events only for the default queue and the \text{async(1)} queue.

5.2. Callbacks Signature

This section describes the signature of event callbacks. All event callbacks have the same signature.

The routine prototypes are available in the header file \text{acc\_prof.h}, which is delivered with the OpenACC implementation.

All callback routines have three arguments. The first argument is a pointer to a struct containing general information; the same struct type is used for all callback events. The second argument is a pointer to a struct containing information specific to that callback event; there is one struct type containing information for data events, another struct type containing information for kernel launch events, and a third struct type for other events, containing essentially no information. The third argument is a pointer to a struct containing information about the application programming interface (API) being used for the specific device. For NVIDIA CUDA devices, this contains CUDA-specific information; for OpenCL devices, this contains OpenCL-specific information. Other interfaces can be supported as they are added by implementations. The prototype for a callback routine is:

\[
\text{typedef void (*acc\_prof\_callback)}
\begin{align*}
&\text{(acc\_prof\_info*},
&\text{acc\_event\_info*},
&\text{acc\_api\_info*});
\end{align*}
\]

In the descriptions, the datatype \text{ssize\_t} means a signed 32-bit integer for a 32-bit binary and a 64-bit integer for a 64-bit binary, the datatype \text{size\_t} means an unsigned 32-bit integer for a
32-bit binary and a 64-bit integer for a 64-bit binary, and the datatype `int` means a 32-bit integer for both 32-bit and 64-bit binaries. A null pointer is the pointer with value zero.

### 5.2.1. First Argument: General Information

The first argument is a pointer to the `acc_prof_info` struct type:

```c
typedef struct acc_prof_info{
    acc_event_t event_type;
    int valid_bytes;
    int version;
    acc_device_t device_type;
    int device_number;
    int thread_id;
    ssize_t async;
    ssize_t async_queue;
    const char* src_file;
    const char* func_name;
    int line_no, end_line_no;
    int func_line_no, func_end_line_no;
} acc_prof_info;
```

The fields are described below.

- **`acc_event_t event_type`** - The event type that triggered this callback. The datatype is the enumeration type `acc_event_t`, described in the previous section. This allows the same callback routine to be used for different events.

- **`int valid_bytes`** - The number of valid bytes in this struct. This allows a library to interface with newer runtimes that may add new fields to the struct at the end while retaining compatibility with older runtimes. A runtime must fill in the `event_type` and `valid_bytes` fields, and must fill in values for all fields with offset less than `valid_bytes`. The value of `valid_bytes` for a struct is recursively defined as:

  
  $$
  \text{valid_bytes(struct)} = \text{offset(lastfield)} + \text{valid_bytes(lastfield)}
  
  \text{valid_bytes(type[n])} = (n-1) \times \text{sizeof(type)} + \text{valid_bytes(type)}
  
  \text{valid_bytes(basictype)} = \text{sizeof(basictype)}
  $$

- **`int version`** - A version number; the value of `_OPENACC`.

- **`acc_device_t device_type`** - The device type corresponding to this event. The datatype is `acc_device_t`, an enumeration type of all the supported accelerator device types, defined in `openacc.h`.

- **`int device_number`** - The device number. Each device is numbered, typically starting at device zero. For applications that use more than one device type, the device numbers may be unique across all devices or may be unique only across all devices of the same device type.

- **`int thread_id`** - The host thread ID making the callback. Host threads are given unique thread ID numbers typically starting at zero. This is not necessarily the same as the OpenMP thread number.
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- `ssize_t async` - The value of the `async()` clause for the directive that triggered this callback.
- `ssize_t async_queue` - If the runtime uses a limited number of asynchronous queues, this field contains the internal asynchronous queue number used for the event.
- `const char* src_file` - A pointer to null-terminated string containing the name of or path to the source file, if known, or a null pointer if not. If the library wants to save the source file name, it should allocate memory and copy the string.
- `const char* func_name` - A pointer to a null-terminated string containing the name of the function in which the event occurred, if known, or a null pointer if not. If the library wants to save the function name, it should allocate memory and copy the string.
- `int line_no` - The line number of the directive or program construct or the starting line number of the OpenACC construct corresponding to the event. A negative or zero value means the line number is not known.
- `int end_line_no` - For an OpenACC construct, this contains the line number of the end of the construct. A negative or zero value means the line number is not known.
- `int func_line_no` - The line number of the first line of the function named in `func_name`. A negative or zero value means the line number is not known.
- `int func_end_line_no` - The last line number of the function named in `func_name`. A negative or zero value means the line number is not known.

5.2.2. Second Argument: Event-Specific Information

The second argument is a pointer to the `acc_event_info` union type.

```c
typedef union acc_event_info{
    acc_event_t event_type;
    acc_data_event_info data_event;
    acc_launch_event_info launch_event;
    acc_other_event_info other_event;
}acc_event_info;
```

The `event_type` field selects which union member to use. The first five members of each union member are identical. The second through fifth members of each union member (`valid_bytes`, `parent_construct`, `implicit`, and `tool_info`) have the same semantics for all event types:

- `int valid_bytes` - The number of valid bytes in the respective struct. (This field is similar used as discussed in Section 5.2.1 First Argument: General Information)
- `acc_construct_t parent_construct` - This field describes the type of construct that caused the event to be emitted. The possible values for this field are defined by the `acc_construct_t` enum, described at the end of this section.
- `int implicit` - This field is set to 1 for any implicit event, such as an implicit wait at a synchronous data construct or synchronous enter data, exit data or update directive. This
field is set to zero when the event is triggered by an explicit directive or call to a runtime API routine.

- **void* tool_info** - This field is used to pass tool-specific information from a _start event to the matching _end event. For a _start event callback, this field will be initialized to a null pointer. The value of this field for a _end event will be the value returned by the library in this field from the matching _start event callback, if there was one, or null otherwise. For events that are neither _start or _end events, this field will be null.

### Data Events

For a data event, as noted in the event descriptions, the second argument will be a pointer to the acc_data_event_info struct.

```c
typedef struct acc_data_event_info{
    acc_event_t event_type;
    int valid_bytes;
    acc_construct_t parent_construct;
    int implicit;
    void* tool_info;
    const char* var_name;
    size_t bytes;
    const void* host_ptr;
    const void* device_ptr;
} acc_data_event_info;
```

The fields specific for a data event are:

- **acc_event_t event_type** - The event type that triggered this callback. The events that use the acc_data_event_info struct are:
  - acc_ev_enqueue_upload_start
  - acc_ev_enqueue_upload_end
  - acc_ev_enqueue_download_start
  - acc_ev_enqueue_download_end
  - acc_ev_create
  - acc_ev_delete
  - acc_ev_alloc
  - acc_ev_free

- **const char* var_name** - A pointer to null-terminated string containing the name of the variable for which this event is triggered, if known, or a null pointer if not. If the library wants to save the variable name, it should allocate memory and copy the string.

- **size_t bytes** - The number of bytes for the data event.

- **const void* host_ptr** - If available and appropriate for this event, this is a pointer to the host data.

- **const void* device_ptr** - If available and appropriate for this event, this is a pointer to the corresponding device data.
Launch Events

For a launch event, as noted in the event descriptions, the second argument will be a pointer to the `acc_launch_event_info` struct.

```c
typedef struct acc_launch_event_info{
    acc_event_t event_type;
    int valid_bytes;
    acc_construct_t parent_construct;
    int implicit;
    void* tool_info;
    const char* kernel_name;
    size_t num_gangs, num_workers, vector_length;
} acc_launch_event_info;
```

The fields specific for a launch event are:

- **acc_event_t event_type** - The event type that triggered this callback. The events that use the `acc_launch_event_info` struct are:
  - `acc_ev_enqueue_launch_start`
  - `acc_ev_enqueue_launch_end`

- **const char* kernel_name** - A pointer to null-terminated string containing the name of the kernel being launched, if known, or a null pointer if not. If the library wants to save the kernel name, it should allocate memory and copy the string.

- **size_t num_gangs, num_workers, vector_length** - The number of gangs, workers and vector lanes created for this kernel launch.

Other Events

For any event that does not use the `acc_data_event_info` or `acc_launch_event_info` struct, the second argument to the callback routine will be a pointer to `acc_other_event_info` struct.

```c
typedef struct acc_other_event_info{
    acc_event_t event_type;
    int valid_bytes;
    acc_construct_t parent_construct;
    int implicit;
    void* tool_info;
} acc_other_event_info;
```

Parent Construct Enumeration

All event structures contain a `parent_construct` member that describes the type of construct that caused the event to be emitted. The purpose of this field is to provide a means to identify
the type of construct emitting the event in the cases where an event may be emitted by multiple
construct types, such as is the case with data and wait events. The possible values for the
parent_construct field are defined in the enumeration type acc_construct_t. In the
case of combined directives, the outermost construct of the combined construct should be specified
as the parent_construct. If the event was emitted as the result of the application making a
call to the runtime api, the value will be acc_construct_runtime_api.

```c
typedef enum acc_construct_t{
    acc_construct_parallel = 0,
    acc_construct_kernels,
    acc_construct_loop,
    acc_construct_data,
    acc_construct_enter_data,
    acc_construct_exit_data,
    acc_construct_host_data,
    acc_construct_atomic,
    acc_construct_declare,
    acc_construct_init,
    acc_construct_shutdown,
    acc_construct_set,
    acc_construct_update,
    acc_construct_routine,
    acc_construct_wait,
    acc_construct_runtime_api,
    acc_construct_serial
}acc_construct_t;
```

5.2.3. Third Argument: API-Specific Information

The third argument is a pointer to the acc_api_info struct type, shown here.

```c
typedef union acc_api_info{
    acc_device_api device_api;
    int valid_bytes;
    acc_device_t device_type;
    int vendor;
    const void* device_handle;
    const void* context_handle;
    const void* async_handle;
}acc_api_info;
```

The fields are described below:

- **acc_device_api device_api** - The API in use for this device. The data type is the
  enumeration acc_device_api, which is described later in this section.

- **int valid_bytes** - The number of valid bytes in this struct. See the discussion above in
  Section [5.2.1 First Argument: General Information]
The OpenACC API

5.3. Loading the Library

- **acc_device_t device_type** - The device type; the datatype is `acc_device_t`, defined in `openacc.h`.
- **int vendor** - An identifier to identify the OpenACC vendor; contact your vendor to determine the value used by that vendor’s runtime.
- **const void* device_handle** - If applicable, this will be a pointer to the API-specific device information.
- **const void* context_handle** - If applicable, this will be a pointer to the API-specific context information.
- **const void* async_handle** - If applicable, this will be a pointer to the API-specific async queue information.

According to the value of `device_api` a library can cast the pointers of the fields `device_handle`, `context_handle` and `async_handle` to the respective device API type. The following device APIs are defined in this interface:

```c
typedef enum acc_device_api{
    acc_device_api_none = 0, /* no device API */
    acc_device_api_cuda,     /* CUDA driver API */
    acc_device_api_opencl,   /* OpenCL API */
    acc_device_api_coi,      /* COI API */
    acc_device_api_other     /* other device API */
} acc_device_api;
```

5.3. Loading the Library

This section describes how a tools library is loaded when the program is run. Four methods are described.

- A tools library may be linked with the program, as any other library is linked, either as a static library or a dynamic library, and the runtime will call a predefined library initialization routine that will register the event callbacks.
- The OpenACC runtime implementation may support a dynamic tools library, such as a shared object for Linux or OS/X, or a DLL for Windows, which is then dynamically loaded at runtime under control of the environment variable `ACC_PROFLIB`.
- Some implementations where the OpenACC runtime is itself implemented as a dynamic library may support adding a tools library using the `LD_PRELOAD` feature in Linux.
- A tools library may be linked with the program, as in the first option, and the application itself can call a library initialization routine that will register the event callbacks.

Callbacks are registered with the runtime by calling `acc_prof_register` for each event as described in Section 5.4 Registering Event Callbacks. The prototype for `acc_prof_register`

```c
extern void acc_prof_register
    (acc_event_t event_type, acc_prof_callback cb,
```
The first argument to `acc_prof_register` is the event for which a callback is being registered
(compare Section 5.1 Events). The second argument is a pointer to the callback routine:

```c
typedef void (*acc_prof_callback)(acc_prof_info*, acc_event_info*, acc_api_info*);
```

The third argument is usually zero (or `acc_reg`). See Section 5.4.2 Disabling and Enabling Callbacks for cases where a nonzero value is used. The argument `acc_register_t` is an enum type:

```c
typedef enum acc_register_t{
    acc_reg = 0,
    acc_toggle = 1,
    acc_toggle_per_thread = 2
} acc_register_t;
```

An example of registering callbacks for launch, upload, and download events is:

```c
acc_prof_register(acc_ev_enqueue_launch_start, prof_launch, 0);
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, 0);
acc_prof_register(acc_ev_enqueue_download_start, prof_data, 0);
```

As shown in this example, the same routine (`prof_data`) can be registered for multiple events. The routine can use the `event_type` field in the `acc_prof_info` structure to determine for what event it was invoked.

### 5.3.1. Library Registration

The OpenACC runtime will invoke `acc_register_library`, passing the addresses of the registration routines `acc_prof_register` and `acc_prof_unregister`, in case that routine comes from a dynamic library. In the third argument it passes the address of the lookup routine `acc_prof_lookup` to obtain the addresses of inquiry functions. No inquiry functions are defined in this profiling interface, but we preserve this argument for future support of sampling-based tools.

Typically, the OpenACC runtime will include a weak definition of `acc_register_library`, which does nothing and which will be called when there is no tools library. In this case, the library can save the addresses of these routines and/or make registration calls to register any appropriate callbacks. The prototype for `acc_register_library` is:

```c
extern void acc_register_library(
    acc_prof_reg register, acc_prof_reg unregister,
    acc_prof_lookup_func lookup);
```

The first two arguments of this routine are of type:
The third argument passes the address to the lookup function `acc_prof_lookup` to obtain the address of interface functions. It is of type:

```c
typedef void (*acc_prof_reg)(acc_event_t event_type, acc_prof_callback cb,
                              acc_register_t info);
```

The argument of the lookup function is a string with the name of the inquiry function. There are no inquiry functions defined for this interface.

### 5.3.2. Statically-Linked Library Initialization

A tools library can be compiled and linked directly into the application. If the library provides an external routine `acc_register_library` as specified in Section 5.3.1 Library Registration, the runtime will invoke that routine to initialize the library.

The sequence of events is:

1. The runtime invokes the `acc_register_library` routine from the library.
2. The `acc_register_library` routine calls `acc_prof_register` for each event to be monitored.
3. `acc_prof_register` records the callback routines.
4. The program runs, and your callback routines are invoked at the appropriate events.

In this mode, only one tool library is supported.

### 5.3.3. Runtime Dynamic Library Loading

A common case is to build the tools library as a dynamic library (shared object for Linux or OS/X, DLL for Windows). In that case, you can have the OpenACC runtime load the library during initialization. This allows you to enable runtime profiling without rebuilding or even relinking your application. The dynamic library must implement a registration routine `acc_register_library` as specified in Section 5.3.1 Library Registration.

The user may set the environment variable `ACC_PROFLIB` to the path to the library will tell the OpenACC runtime to load your dynamic library at initialization time:

Bash:

```bash
export ACC_PROFLIB=/home/user/lib/myprof.so
./myapp
```
or

```bash
ACC_PROFLIB=/home/user/lib/myprof.so ./myapp
```
C-shell:
```
setenv ACC_PROFLIB /home/user/lib/myprof.so
./myapp
```

When the OpenACC runtime initializes, it will read the `ACC_PROFLIB` environment variable (with `getenv`). The runtime will open the dynamic library (using `dlopen` or `LoadLibraryA`); if the library cannot be opened, the runtime may abort, or may continue execution with or without an error message. If the library is successfully opened, the runtime will get the address of the `acc_register_library` routine (using `dlsym` or `GetProcAddress`). If this routine is resolved in the library, it will be invoked passing in the addresses of the registration routine `acc_prof_register`, the deregistration routine `acc_prof_unregister`, and the lookup routine `acc_prof_lookup`. The registration routine in your library, `acc_register_library`, should register the callbacks by calling the `register` argument, and should save the addresses of the arguments (`register`, `unregister`, and `lookup`) for later use, if needed.

The sequence of events is:

1. Initialization of the OpenACC runtime.
2. OpenACC runtime reads `ACC_PROFLIB`.
3. OpenACC runtime loads the library.
4. OpenACC runtime calls the `acc_register_library` routine in that library.
5. Your `acc_register_library` routine calls `acc_prof_register` for each event to be monitored.
6. `acc_prof_register` records the callback routines.
7. The program runs, and your callback routines are invoked at the appropriate events.

If supported, paths to multiple dynamic libraries may be specified in the `ACC_PROFLIB` environment variable, separated by semicolons (`;`). The OpenACC runtime will open these libraries and invoke the `acc_register_library` routine for each, in the order they appear in `ACC_PROFLIB`.

### 5.3.4. Preloading with LD_PRELOAD

The implementation may also support dynamic loading of a tools library using the `LD_PRELOAD` feature available in some systems. In such an implementation, you need only specify your tools library path in the `LD_PRELOAD` environment variable before executing your program. The OpenACC runtime will invoke the `acc_register_library` routine in your tools library at initialization time. This requires that the OpenACC runtime include a dynamic library with a default (empty) implementation of `acc_register_library` that will be invoked in the normal case where there is no `LD_PRELOAD` setting. If an implementation only supports static linking, or if the application is linked without dynamic library support, this feature will not be available.

Bash:
```
export LD_PRELOAD=/home/user/lib/myprof.so
./myapp
```
or
```
LD_PRELOAD=/home/user/lib/myprof.so ./myapp
```
C-shell:

```bash
    setenv LD_PRELOAD /home/user/lib/myprof.so
    ./myapp
```

The sequence of events is:

1. The operating system loader loads the library specified in `LD_PRELOAD`.
2. The call to `acc_register_library` in the OpenACC runtime is resolved to the routine in the loaded tools library.
3. OpenACC runtime calls the `acc_register_library` routine in that library.
4. Your `acc_register_library` routine calls `acc_prof_register` for each event to be monitored.
5. `acc_prof_register` records the callback routines.
6. The program runs, and your callback routines are invoked at the appropriate events.

In this mode, only a single tools library is supported, since only one `acc_register_library` initialization routine will get resolved by the dynamic loader.

### 5.3.5. Application-Controlled Initialization

An alternative to default initialization is to have the application itself call the library initialization routine, which then calls `acc_prof_register` for each appropriate event. The library may be statically linked to the application or your application may dynamically load the library.

The sequence of events is:

1. Your application calls the library initialization routine.
2. The library initialization routine calls `acc_prof_register` for each event to be monitored.
3. `acc_prof_register` records the callback routines.
4. The program runs, and your callback routines are invoked at the appropriate events.

In this mode, multiple tools libraries can be supported, with each library initialization routine invoked by the application.

### 5.4. Registering Event Callbacks

This section describes how to register and unregister callbacks, temporarily disabling and enabling callbacks, the behavior of dynamic registration and unregistration, and requirements on an OpenACC implementation to correctly support the interface.
5.4.1. Event Registration and Unregistration

The library must call the registration routine \texttt{acc_prof_register} to register each callback with the runtime. A simple example:

```
extern void prof_data(acc_prof_info* profinfo, 
acc_event_info* eventinfo, acc_api_info* apiinfo);
extern void prof_launch(acc_prof_info* profinfo, 
acc_event_info* eventinfo, acc_api_info* apiinfo);
...
```

```c
void acc_register_library()
{
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, 0);
acc_prof_register(acc_ev_enqueue_download_start, prof_data, 0);
acc_prof_register(acc_ev_enqueue_launch_start, prof_launch, 0);
}
```

In this example the \texttt{prof_data} routine will be invoked for each data upload and download event, and the \texttt{prof_launch} routine will be invoked for each launch event. The \texttt{prof_data} routine might start out with:

```c
void prof_data(acc_prof_info* profinfo, 
acc_event_info* eventinfo, acc_api_info* apiinfo){
acc_data_event_info* datainfo;
datainfo = (acc_data_event_info*)eventinfo;
switch( datainfo->event_type ){
  case acc_ev_enqueue_upload_start : ...
}
}
```

### Multiple Callbacks

Multiple callback routines can be registered on the same event:

```
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, 0);
acc_prof_register(acc_ev_enqueue_upload_start, prof_up, 0);
```

For most events, the callbacks will be invoked in the order in which they are registered. However, \texttt{end} events, named \texttt{acc_ev..._end}, invoke callbacks in the reverse order. Essentially, each event has an ordered list of callback routines. A new callback routine is appended to the tail of the list for that event. For most events, that list is traversed from the head to the tail, but for \texttt{end} events, the list is traversed from the tail to the head. If a callback is registered, then later unregistered, then later still registered again, the second registration is considered to be a new callback, and the callback routine will then be appended to the tail of the callback list for that event.
Unregistering

A matching call to `acc_prof_unregister` will remove that routine from the list of callback
routines for that event.

```c
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, 0);
// prof_data is on the callback list for acc_ev_enqueue_upload_start
...
acc_prof_unregister(acc_ev_enqueue_upload_start, prof_data, 0);
// prof_data is removed from the callback list
// for acc_ev_enqueue_upload_start
```

Each entry on the callback list must also have a `ref` count. This keeps track of how many times
this routine was added to this event’s callback list. If a routine is registered `n` times, it must be
unregistered `n` times before it is removed from the list. Note that if a routine is registered multiple
times for the same event, its `ref` count will be incremented with each registration, but it will only be
invoked once for each event instance.

5.4.2. Disabling and Enabling Callbacks

A callback routine may be temporarily disabled on the callback list for an event, then later re-
enabled. The behavior is slightly different than unregistering and later re-registering that event.
When a routine is disabled and later re-enabled, the routine’s position on the callback list for that
event is preserved. When a routine is unregistered and later re-registered, the routine’s position on
the callback list for that event will move to the tail of the list. Also, unregistering a callback must be
done `n` times if the callback routine was registered `n` times. In contrast, disabling, and enabling an
event sets a toggle. Disabling a callback will immediately reset the toggle and disable calls to that
routine for that event, even if it was enabled multiple times. Enabling a callback will immediately
set the toggle and enable calls to that routine for that event, even if it was disabled multiple times.
Registering a new callback initially sets the toggle.

A call to `acc_prof_unregister` with a value of `acc_toggle` as the third argument will dis-
able callbacks to the given routine. A call to `acc_prof_register` with a value of `acc_toggle`
as the third argument will enable those callbacks.

```c
acc_prof_unregister(acc_ev_enqueue_upload_start, prof_data, acc_toggle);
// prof_data is disabled
...
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, acc_toggle);
// prof_data is re-enabled
```

A call to either `acc_prof_unregister` or `acc_prof_register` to disable or enable a call-
back when that callback is not currently registered for that event will be ignored with no error.
All callbacks for an event may be disabled (and re-enabled) by passing `NULL` to the second argument
and `acc_toggle` to the third argument of `acc_prof_unregister` (and `acc_prof_register`).
This sets a toggle for that event, which is distinct from the toggle for each callback for that event. While the event is disabled, no callbacks for that event will be invoked. Callbacks for that event can be registered, unregistered, enabled, and disabled while that event is disabled, but no callbacks will be invoked for that event until the event itself is enabled. Initially, all events are enabled.

```c
acc_prof_unregister(acc_ev_enqueue_upload_start, prof_data, acc_toggle);
// prof_data is disabled
...
acc_prof_unregister(acc_ev_enqueue_upload_start, NULL, acc_toggle);
// acc_ev_enqueue_upload_start callbacks are disabled
...
acc_prof_register(acc_ev_enqueue_upload_start, prof_data, acc_toggle);
// prof_data is re-enabled, but
// acc_ev_enqueue_upload_start callbacks still disabled
...
acc_prof_register(acc_ev_enqueue_upload_start, prof_up, 0);
// prof_up is registered and initially enabled, but
// acc_ev_enqueue_upload_start callbacks still disabled
...
acc_prof_register(acc_ev_enqueue_upload_start, NULL, acc_toggle);
// acc_ev_enqueue_upload_start callbacks are enabled
```

Finally, all callbacks can be disabled (and enabled) by passing the argument list `(0, NULL, acc_toggle)` to `acc_prof_unregister` (and `acc_prof_register`). This sets a global toggle disabling all callbacks, which is distinct from the toggle enabling callbacks for each event and the toggle enabling each callback routine. The behavior of passing zero as the first argument and a non-NULL value as the second argument to `acc_prof_unregister` or `acc_prof_register` is not defined, and may be ignored by the runtime without error.

All callbacks can be disabled (or enabled) for just the current thread by passing the argument list `(0, NULL, acc_toggle_per_thread)` to `acc_prof_unregister` (and `acc_prof_register`). This is the only thread-specific interface to `acc_prof_register` and `acc_prof_unregister`, and all other calls to register, unregister, enable, or disable callbacks affect all threads in the application.

### 5.5. Advanced Topics

This section describes advanced topics such as dynamic registration and changes of the execution state for callback routines as well as the runtime and tool behavior for multiple host threads.
5.5.1. Dynamic Behavior

Callback routines may be registered or unregistered, enabled or disabled at any point in the execution of the program. Calls may appear in the library itself, during the processing of an event. The OpenACC runtime must allow for this case, where the callback list for an event is modified while that event is being processed.

Dynamic Registration and Unregistration

Calls to `acc_register` and `acc_unregister` may occur at any point in the application. A callback routine can be registered or unregistered from a callback routine, either the same routine or another routine, for a different event or the same event for which the callback was invoked. If a callback routine is registered for an event while that event is being processed, then the new callback routine will be added to the tail of the list of callback routines for this event. Some events (the `_end`) events process the callback routines in reverse order, from the tail to the head. For those events, adding a new callback routine will not cause the new routine to be invoked for this instance of the event. The other events process the callback routines in registration order, from the head to the tail. Adding a new callback routine for such a event will cause the runtime to invoke that newly registered callback routine for this instance of the event. Both the runtime and the library must implement and expect this behavior.

If an existing callback routine is unregistered for an event while that event is being processed, that callback routine is removed from the list of callbacks for this event. For any event, if that callback routine had not yet been invoked for this instance of the event, it will not be invoked.

Registering and unregistering a callback routine is a global operation and affects all threads, in a multithreaded application. See Section 5.4.1 Multiple Callbacks.

Dynamic Enabling and Disabling

Calls to `acc_register` and `acc_unregister` to enable and disable a specific callback for an event, enable or disable all callbacks for an event, or enable or disable all callbacks may occur at any point in the application. A callback routine can be enabled or disabled from a callback routine, either the same routine or another routine, for a different event or the same event for which the callback was invoked. If a callback routine is enabled for an event while that event is being processed, then the new callback routine will be immediately enabled. If it appears on the list of callback routines closer to the head (for `_end` events) or closer to the tail (for other events), that newly-enabled callback routine will be invoked for this instance of this event, unless it is disabled or unregistered before that callback is reached.

If a callback routine is disabled for an event while that event is being processed, that callback routine is immediately disabled. For any event, if that callback routine had not yet been invoked for this instance of the event, it will not be invoked, unless it is enabled before that callback routine is reached in the list of callbacks for this event. If all callbacks for an event are disabled while that event is being processed, or all callbacks are disabled for all events while an event is being processed, then when this callback routine returns, no more callbacks will be invoked for this instance of the event.

Registering and unregistering a callback routine is a global operation and affects all threads, in a multithreaded application. See Section 5.4.1 Multiple Callbacks.
5.5.2. OpenACC Events During Event Processing

OpenACC events may occur during event processing. This may be because of OpenACC API routine calls or OpenACC constructs being reached during event processing, or because of multiple host threads executing asynchronously. Both the OpenACC runtime and the tool library must implement the proper behavior.

5.5.3. Multiple Host Threads

Many programs that use OpenACC also use multiple host threads, such as programs using the OpenMP API. The appearance of multiple host threads affects both the OpenACC runtime and the tools library.

Runtime Support for Multiple Threads

The OpenACC runtime must be thread-safe, and the OpenACC runtime implementation of this tools interface must also be thread-safe. All threads use the same set of callbacks for all events, so registering a callback from one thread will cause all threads to execute that callback. This means that managing the callback lists for each event must be protected from multiple simultaneous updates. This includes adding a callback to the tail of the callback list for an event, removing a callback from the list for an event, and incrementing or decrementing the ref count for a callback routine for an event.

In addition, one thread may register, unregister, enable, or disable a callback for an event while another thread is processing the callback list for that event asynchronously. The exact behavior may be dependent on the implementation, but some behaviors are expected and others are disallowed. In the following examples, there are three callbacks, A, B, and C, registered for event E in that order, where callbacks A and B are enabled and callback C is temporarily disabled. Thread T1 is dynamically modifying the callbacks for event E while thread T2 is processing an instance of event E.

- Suppose thread T1 unregisters or disables callback A for event E. Thread T2 may or may not invoke callback A for this event instance, but it must invoke callback B; if it invokes callback A, that must precede the invocation of callback B.
- Suppose thread T1 unregisters or disables callback B for event E. Thread T2 may or may not invoke callback B for this event instance, but it must invoke callback A; if it invokes callback B, that must follow the invocation of callback A.
- Suppose thread T1 unregisters or disables callback A and then unregisters or disables callback B for event E. Thread T2 may or may not invoke callback A and may or may not invoke callback B for this event instance, but if it invokes both callbacks, it must invoke callback A before it invokes callback B.
- Suppose thread T1 unregisters or disables callback B and then unregisters or disables callback A for event E. Thread T2 may or may not invoke callback A and may or may not invoke callback B for this event instance, but if it invokes callback B, it must have invoked callback A for this event instance.
- Suppose thread T1 is registering a new callback D for event E. Thread T2 may or may not
invoke callback D for this event instance, but it must invoke both callbacks A and B. If it
invokes callback D, that must follow the invocations of A and B.

- Suppose thread T1 is enabling callback C for event E. Thread T2 may or may not invoke
callback C for this event instance, but it must invoke both callbacks A and B. If it invokes
callback C, that must follow the invocations of A and B.

The **acc_prof_info** struct has a **thread_id** field, which the runtime must set to a unique
value for each host thread, though it need not be the same as the OpenMP threadnum value.

**Library Support for Multiple Threads**

The tool library must also be thread-safe. The callback routine will be invoked in the context of the
thread that reaches the event. The library may receive a callback from a thread T2 while it’s still
processing a callback, from the same event type or from a different event type, from another thread
T1. The **acc_prof_info** struct has a **thread_id** field, which the runtime must set to a unique
value for each host thread.

If the tool library uses dynamic callback registration and unregistration, or callback disabling and
enabling, recall that unregistering or disabling an event callback from one thread will unregister or
disable that callback for all threads, and registering or enabling an event callback from any thread
will register or enable it for all threads. If two or more threads register the same callback for the
same event, the behavior is the same as if one thread registered that callback multiple times; see
Section 5.4.1 Multiple Callbacks. The **acc_unregister** routine must be called as many times
as **acc_register** for that callback/event pair in order to totally unregister it. If two threads
register two different callback routines for the same event, unless the order of the registration calls
is guaranteed by some synchronization method, the order in which the runtime sees the registration
may differ for multiple runs, meaning the order in which the callbacks occur will differ as well.
6. Glossary

Clear and consistent terminology is important in describing any programming model. We define here the terms you must understand in order to make effective use of this document and the associated programming model.

**Accelerator** – a special-purpose co-processor attached to a CPU and to which the CPU can offload data and compute kernels to perform compute-intensive calculations.

**Accelerator routine** – a C or C++ function or Fortran subprogram compiled for the accelerator with the `routine` directive.

**Accelerator thread** – a thread of execution that executes on the accelerator; a single vector lane of a single worker of a single gang.

**Aggregate datatype** – an array or structure datatype, or any non-scalar datatype. In Fortran, aggregate datatypes include arrays and derived types. In C, aggregate datatypes include fixed size arrays, targets of pointers, structs, and unions. In C++, aggregate datatypes include fixed size arrays, targets of pointers, classes, structs, and unions.

**Aggregate variables** – an array or structure variable, or a variable of any non-scalar datatype.

**Async-argument** – an `async-argument` is a nonnegative scalar integer expression (`int` for C or C++, `integer` for Fortran), or one of the special async values `acc_async_noval` or `acc_async_sync`.

**Barrier** – a type of synchronization where all parallel execution units or threads must reach the barrier before any execution unit or thread is allowed to proceed beyond the barrier; modeled after the starting barrier on a horse race track.

**Compute intensity** – for a given loop, region, or program unit, the ratio of the number of arithmetic operations performed on computed data divided by the number of memory transfers required to move that data between two levels of a memory hierarchy.

**Construct** – a directive and the associated statement, loop, or structured block, if any.

**Compute construct** – a `parallel construct`, `kernels construct`, or `serial construct`.

**Compute region** – a `parallel region`, `kernels region`, or `serial region`.

**CUDA** – the CUDA environment from NVIDIA is a C-like programming environment used to explicitly control and program an NVIDIA GPU.

**Current device** – the device represented by the `acc-device-type-var` and `acc-device-num-var` ICVs.

**Current device type** – the device type represented by the `acc-device-type-var` ICV.

**Data lifetime** – the lifetime of a data object on the device, which may begin at the entry to a data region, or at an `enter data` directive, or at a data API call such as `acc_copyin` or `acc_create`, and which may end at the exit from a data region, or at an `exit data` directive, or at a data API call such as `acc_delete`, `acc_copyout`, or `acc_shutdown`, or at the end of the program execution.
**Data region** – a *region* defined by a *data* construct, or an implicit data region for a function or subroutine containing Accelerator directives. Data constructs typically allocate device memory and copy data from host to device memory upon entry, and copy data from device to host memory and deallocate device memory upon exit. Data regions may contain other data regions and compute regions.

**Device** – a general reference to any type of accelerator.

**Default asynchronous queue** – the asynchronous activity queue represented in the `acc-default-async-var` ICV

**Device memory** – memory attached to an accelerator, logically and physically separate from the host memory.

**Directive** – in C or C++, a `#pragma`, or in Fortran, a specially formatted comment statement, that is interpreted by a compiler to augment information about or specify the behavior of the program.

**DMA** – Direct Memory Access, a method to move data between physically separate memories; this is typically performed by a DMA engine, separate from the host CPU, that can access the host physical memory as well as an IO device or other physical memory.

**GPU** – a Graphics Processing Unit; one type of accelerator device.

**GPGPU** – General Purpose computation on Graphics Processing Units.

**Host** – the main CPU that in this context has an attached accelerator device. The host CPU controls the program regions and data loaded into and executed on the device.

**Host thread** – a thread of execution that executes on the host.

**Implicit data region** – the data region that is implicitly defined for a Fortran subprogram or C function. A call to a subprogram or function enters the implicit data region, and a return from the subprogram or function exits the implicit data region.

**Kernel** – a nested loop executed in parallel by the accelerator. Typically the loops are divided into a parallel domain, and the body of the loop becomes the body of the kernel.

**Kernels region** – a *region* defined by a *kernels* construct. A kernels region is a structured block which is compiled for the accelerator. The code in the kernels region will be divided by the compiler into a sequence of kernels; typically each loop nest will become a single kernel. A kernels region may require device memory to be allocated and data to be copied from host to device upon region entry, and data to be copied from device to host memory and device memory deallocated upon exit.

**Level of parallelism** – The possible levels of parallelism in OpenACC are gang, worker, vector, and sequential. One or more of gang, worker, and vector parallelism may be specified on a loop construct. Sequential execution corresponds to no parallelism. The `gang`, `worker`, `vector`, and `seq` clauses specify the level of parallelism for a loop.

**Local memory** – the memory associated with the local thread.

**Local thread** – the host thread or the accelerator thread that executes an OpenACC directive or construct.

**Loop trip count** – the number of times a particular loop executes.

**MIMD** – a method of parallel execution (Multiple Instruction, Multiple Data) where different execution units or threads execute different instruction streams asynchronously with each other.
OpenCL — short for Open Compute Language, a developing, portable standard C-like programming environment that enables low-level general-purpose programming on GPUs and other accelerators.

Orphaned loop construct - a loop construct that is not lexically contained in any compute construct, that is, that has no parent compute construct.

Parallel region — a region defined by a parallel construct. A parallel region is a structured block which is compiled for the accelerator. A parallel region typically contains one or more work-sharing loops. A parallel region may require device memory to be allocated and data to be copied from host to device upon region entry, and data to be copied from device to host memory and device memory deallocated upon exit.

Parent compute construct — for a loop construct, the parallel, kernels, or serial construct that lexically contains the loop construct and is the innermost compute construct that contains that loop construct, if any.

Private data — with respect to an iterative loop, data which is used only during a particular loop iteration. With respect to a more general region of code, data which is used within the region but is not initialized prior to the region and is re-initialized prior to any use after the region.

Procedure — in C or C++, a function in the program; in Fortran, a subroutine or function.

Region — all the code encountered during an instance of execution of a construct. A region includes any code in called routines, and may be thought of as the dynamic extent of a construct. This may be a parallel region, kernels region, serial region, data region or implicit data region.

Scalar — a variable of scalar datatype. In Fortran, scalars must not have allocatable or pointer attributes.

Scalar datatype — an intrinsic or built-in datatype that is not an array or aggregate datatype. In Fortran, scalar datatypes are integer, real, double precision, complex, or logical. In C, scalar datatypes are char (signed or unsigned), int (signed or unsigned, with optional short, long or long long attribute), enum, float, double, long double, _Complex (with optional float or long attribute), or any pointer datatype. In C++, scalar datatypes are char (signed or unsigned), wchar_t, int (signed or unsigned, with optional short, long or long long attribute), enum, bool, float, double, long double, or any pointer datatype. Not all implementations or targets will support all of these datatypes.

Serial region — a region defined by a serial construct. A serial region is a structured block which is compiled for the accelerator. A serial region contains code that is executed by one vector lane of one worker in one gang. A serial region may require device memory to be allocated and data to be copied from host to device upon region entry, and data to be copied from device to host memory and device memory deallocated upon exit.

SIMD — A method of parallel execution (single-instruction, multiple-data) where the same instruction is applied to multiple data elements simultaneously.

SIMD operation — a vector operation implemented with SIMD instructions.

Structured block — in C or C++, an executable statement, possibly compound, with a single entry at the top and a single exit at the bottom. In Fortran, a block of executable statements with a single entry at the top and a single exit at the bottom.

Thread — On a host processor, a thread is defined by a program counter and stack location; several host threads may comprise a process and share host memory. On an accelerator, a thread is any one vector lane of one worker of one gang on the device.
Vector operation – a single operation or sequence of operations applied uniformly to each element of an array.

Visible device copy – a copy of a variable, array, or subarray allocated in device memory that is visible to the program unit being compiled.
A. Recommendations for Implementors

This section gives recommendations for standard names and extensions to use for implementations for specific targets and target platforms, to promote portability across such implementations, and recommended options that programmers find useful. While this appendix is not part of the OpenACC specification, implementations that provide the functionality specified herein are strongly recommended to use the names in this section. The first subsection describes target devices, such as NVIDIA GPUs. The second subsection describes additional API routines for target platforms, such as CUDA and OpenCL. The third subsection lists several recommended options for implementations.

A.1. Target Devices

A.1.1. NVIDIA GPU Targets

This section gives recommendations for implementations that target NVIDIA GPU devices.

Accelerator Device Type

These implementations should use the name acc_device_nvidia for the acc_device_t type or return values from OpenACC Runtime API routines.

ACC_DEVICE_TYPE

An implementation should use the case-insensitive name nvidia for the environment variable ACC_DEVICE_TYPE.

device_type clause argument

An implementation should use the case-insensitive name nvidia as the argument to the device_type clause.

A.1.2. AMD GPU Targets

This section gives recommendations for implementations that target AMD GPUs.
Accelerator Device Type

These implementations should use the name `acc_device_radeon` for the `acc_device_t` type or return values from OpenACC Runtime API routines.

ACC_DEVICE_TYPE

These implementations should use the case-insensitive name `radeon` for the environment variable `ACCDEVICE_TYPE`.

device_type clause argument

An implementation should use the case-insensitive name `radeon` as the argument to the `device_type` clause.

A.2. API Routines for Target Platforms

These runtime routines allow access to the interface between the OpenACC runtime API and the underlying target platform. An implementation may not implement all these routines, but if it provides this functionality, it should use these function names.

A.2.1. NVIDIA CUDA Platform

This section gives runtime API routines for implementations that target the NVIDIA CUDA Runtime or Driver API.

`acc_get_current_cuda_device`

**Summary** The `acc_get_current_cuda_device` routine returns the NVIDIA CUDA device handle for the current device.

**Format**

C or C++:

```c
void* acc_get_current_cuda_device ();
```

`acc_get_current_cuda_context`

**Summary** The `acc_get_current_cuda_context` routine returns the NVIDIA CUDA context handle in use for the current device.
Format

C or C++:

```c
void* acc_get_current_cuda_context ();
```

**acc.get.cuda.stream**

**Summary** The `acc_get_cuda_stream` routine returns the NVIDIA CUDA stream handle in use for the current device for the specified async value.

Format

C or C++:

```c
void* acc_get_cuda_stream ( int async );
```

**acc.set.cuda.stream**

**Summary** The `acc_set_cuda_stream` routine sets the NVIDIA CUDA stream handle the current device for the specified async value.

Format

C or C++:

```c
int acc_set_cuda_stream ( int async, void* stream );
```

**A.2.2. OpenCL Target Platform**

This section gives runtime API routines for implementations that target the OpenCL API on any device.

**acc.get.current.opencl.device**

**Summary** The `acc_get_current_opencl_device` routine returns the OpenCL device handle for the current device.

Format

C or C++:

```c
void* acc_get_current_opencl_device ();
```

**acc.get.current.opencl.context**

**Summary** The `acc_get_current_opencl_context` routine returns the OpenCL context handle in use for the current device.
Format

C or C++:

```c
void* acc_get_current_opencl_context();
```

**acc_get_opencl_queue**

**Summary**  The *acc_get_opencl_queue* routine returns the OpenCL command queue handle in use for the current device for the specified async value.

Format

C or C++:

```c
cl_command_queue acc_get_opencl_queue ( int async );
```

**acc_set_opencl_queue**

**Summary**  The *acc_set_opencl_queue* routine returns the OpenCL command queue handle in use for the current device for the specified async value.

Format

C or C++:

```c
void acc_set_opencl_queue ( int async, cl_command_queue cmdqueue );
```

### A.2.3. C Pointer in Present clause

This revision of OpenACC clarifies the construct:

```c
void test(int n ){
  float* p;
  ...
  #pragma acc data present(p)
  {
    // code here...
  }
```

This example tests whether the pointer *p* itself is present on the device. Implementations before this revision commonly implemented this by testing whether the pointer target *p[0]* was present on the device, and this appears in many programs assuming such. Until such programs are modified to comply with this revision, an option to implement `present(p)` as `present(p[0])` for C pointers may be helpful to users.
A.2.4. Autoscooping

If an implementation implements autoscooping to automatically determine variables that are private to a compute region or to a loop, or to recognize reductions in a compute region or a loop, an option to print a message telling what variables were affected by the analysis would be helpful to users. An option to disable the autoscooping analysis would be helpful to promote program portability across implementations.
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